

# **Universal control module**

### **Operating Instructions**



Keep for reference!

Software version: from version 11.15



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## 1 General notes

### 1.1 Structure of the operating instructions

Before installation and start-up, read this manual carefully to ensure correct use! We emphasize that these operating instructions apply to specific units only, and are in no way valid for the complete system!

Use these operating instructions to work safely with and on the device. They contain safety instructions that must be complied with as well as information that is required for failure-free operation of the device.

Keep these operating instructions together with the device. It must be ensured that all persons that are to work on the device can refer to the operating instructions at any time.

Keep the operating instructions for continued use. They must be passed-on to all successive owners, users and final customers.

### 1.2 Target group

The operating instructions address persons entrusted with planning, installation, commissioning and maintenance and servicing and who have the corresponding qualifications and skills for their job.

### 1.3 Exclusion of liability

Concurrence between the contents of these operating instructions and the described hardware and software in the device has been examined. It is still possible that non-compliances exist; no guarantee is assumed for complete conformity. To allow for future developments, construction methods and technical data given are subject to alteration. We do not accept any liability for possible errors or omissions in the information contained in data, illustrations or drawings provided. We accept no liability for damage caused by misuse, incorrect use, improper use or as a consequence of unauthorized repairs or modifications.

### 1.4 Copyright

These operating instructions contain copyright protected information. The operating instructions may be neither completely nor partially photocopied, reproduced, translated or put on data medium without previous explicit consent. Infringements are liable for damages. All rights reserved, including those that arise through patent issue or registration on a utility model.

## 2 Safety instructions

This chapter contains instructions to prevent personal injury and property damage. These instructions do not lay claim to completeness. In case of questions and problems, please consult our company technicians.

### 2.1 Intended use

The equipment is to be used solely for the purposes specified and confirmed in the order. Any other use above and beyond this is considered not for the intended purpose unless agreed otherwise by contract. The manufacturer will not be liable for any damage resulting from this. The individual or company using it bears the sole risk.

Reading these operating instructions and complying with all contained instructions - especially the safety notifications contained therein - are considered part of intended use. To consider is also the manual of attached components. Not the manufacturer, rather the operator of the device is liable for any personal harm or material damage arising from non-intended use!





### 2.2 Explanations of symbols

Safety instructions are highlighted with warning triangles and are depicted according to the degree of hazard as follows.

	Attention! General hazardous area. Death or severe injury or significant property damage can occur if the corresponding precautions are not taken!
<u>A</u>	<b>Danger due to electric current</b> Danger by dangerous, electric voltage! Death or severe injury can occur if the corresponding precautions are not taken!
1	Information Important additional information and advice for user.

### 2.3 Product safety

The device conforms to the state of the art at the time of delivery and is fundamentally considered to be reliable. The device and its accessories must only be used in a flawless condition and installed and operated in compliance with the assembly instructions and/or operating instructions. Operating outside the device's technical specifications (P name plate and attachment / technical data) can lead to a defect in the device and additional damage!

In the case of a malfunction or a failure of the equipment check all functions with alarms in order to prevent injury to persons or property. Note possibility of back-up operation. If used in intensive animal environments, any malfunctions in the air supply must be detected as soon as possible to prevent the development of a life-threatening situation for the animals. The design and installation of the system must comply with local regulations and directives. In Germany these include DIN VDE 0100, the animal protection and the keeping of working animals ordinance and the pig-keeping ordinance etc. Also note the instructions of AEL, DLG, VdS.

### 2.4 Requirements placed on the personnel / due diligence

Persons entrusted with the planning, installation, commissioning and maintenance and servicing in connection with the frequency inverter must have the corresponding qualifications and skills for these jobs.

In addition, they must be knowledgeable about the safety regulations, EU directives, rules for the prevention of accidents and the corresponding national as well as regional and in-house regulations. Personnel to be trained or instructed and apprentices are only permitted to work on the device under the supervision of an experienced person. This also applies to personnel undergoing general training. Comply with the legal minimum age.

### 2.5 Start-up and during operation



#### Attention!

- During commissioning, unexpected and hazardous conditions can arise in the entire installation due to defective adjustments, defective components or incorrect electrical connections. Remove all persons and objects from the hazardous area.
- During operation, the device must be closed or installed in a control cabinet. Fuses may only be replaced by new ones and must not be repaired or bypassed. The data for the maximum line fuse are to be considered absolutely (@ Technical data). Use only fuses specified in schematic diagrams.
- Any faults detected in the electric system/modules/operating equipment must be corrected immediately. If these faults are not corrected, the device/system is potentially very dangerous. The device/system must therefore not be operated when it is faulty.
- Pay attention to smooth, low vibration running of the motor/fan, the appropriate instructions in the drive documentation must be observed!



### 2.6 Work on the device



#### Information

Mounting, electrical connection, and start-up operation may only be carried out by an electrical specialist in accordance with electrotechnical regulations (e.g. EN 50110 or EN 60204)!



#### Danger due to electric current

It is generally forbidden to carry out work on electrical live parts. Protection class of the device when open is IP00! It is possible to touch hazardous voltages directly. The safe isolation from the supply must be checked using a **two-pole** voltage detector.



#### Attention!

Automatically restart after a power failure or mains disconnection!

### 2.7 Modifications / interventions in the device



### Attention!

For reasons of safety, no unauthorized interventions or modifications may be made on the device. All planned modifications must be authorized by the manufacturer in writing.

Only use the manufacturer's original spare parts / wearing parts / accessories. These parts are specially designed for this device. If parts from other sources are used, there is no guarantee that they are designed and produced for the proper loads and with the required level of safety. Parts and special equipment not supplied by the manufacturer are not approved for use.

### 2.8 Operator's obligation of diligence

- The contractor or owner must also ensure that the electric systems and equipment are operated and maintained in accordance with electro-technical regulations.
- The owner is obliged to ensure that the device is operated in perfect working order only.
- The device may only be used as intended (@ "area of application").
- You must periodically examine the safety equipment for their properly functioning condition.
- The assembly instructions and/or operating instructions are always readily available at the location where the device is being used, are complete and are in legible condition.
- These persons are regularly instructed in all applicable questions regarding occupational safety and environmental protection and are knowledgeable regarding the assembly instructions and/or operating instructions and, especially, are familiar with the safety instructions contained therein.
- All safety and warning notices attached to the device are never removed and remain legible.

### 2.9 Employment of external personnel

Maintenance and service work are frequently carried out by external employees who often do not recognize the specific situations and the thus resulting dangers. These persons must be comprehensively informed about the hazards in their area of activity.

You must monitor their working methods in order to intervene in good time if necessary.



## 3 **Product overview**

### 3.1 Operational area

The purpose of the device is to reach and maintain the target values set. To accomplish this, the measured actual value (sensor value) is compared with the adjusted target value, and the controlled value is deduced from this.

The device has two separate control circuits and two sensor inputs (0 - 10 V, 4 - 20 mA, KTY 81-210, PT 1000).

Speed controllers for fans or fans with an integrated controller can be activated via the 0 - 10 V signal or the parallel option of the MODBUS Master interface.

### 3.2 Maintenance

The device must be checked for soiling and, if necessary, cleaned in periodic intervals.

### 3.3 Transport

- The device is packed ex factory to suit the transport method previously agreed.
- Always use the original packaging materials when transporting the device.
- Avoid shocks and impacts to the device during the transport.
- During manual handling the human lifting and carrying restrictions must be observed and adhered to.

### 3.4 Storage

- The device must be stored in its original packaging in a dry and weather-proof room.
- Avoid exposure to extreme heat and cold.
- Avoid over-long storage periods (we recommend a maximum of one year).

### 3.5 Disposal / recycling



Disposal must be carried out professionally and in an environmentally friendly way in accordance with the respective national legal stipulations.

 $\triangleright$  Separate the materials by type and in an environmentally friendly way.

 $\triangleright$  If necessary, commission a specialist company with the waste disposal.



## 4 Mounting

### 4.1 General notes



Attention! The following points must be complied with during the mechanical installation to avoid causing a defect in the device due to assembly errors or environmental influences:

- Before installation remove the device from the packing and check for any possible shipping damage!
- Assemble the device on a clean and stable base. Do not distort during assembly! Use the appropriate mounting devices for proper installation of the unit!
- Do not mount equipment on vibrating base!
- When mounted onto lightweight walls, there must be no impermissibly high vibrations or shock loads. Any banging shut of doors that are integrated into these lightweight walls, can result in extremely high shock loads. Therefore, we advise you to decouple the devices from the wall.
- Do not allow drilling chips, screws and other foreign bodies to reach the device interior!
- The device should be installed in a location where it will not be disturbed, but at the same time can be easily accessed!
- Depending on the housing model use supplied stoppers for cable inlets, cut off necessary cable inlets respectively to the cable diameter. Or alternative use cable inlet for cable glands. Any cable ducts openings not used must be sealed!
- Care must be taken to avoid direct radiation from the sun!
- The device is designed for vertical installation (cable inlet down). A horizontal or reclined installation is only permissible after technical release of the manufacturer!
- Be sure to observe proper heat dissipation (@Technical data, heat dissipation).

### 4.2 Outdoor installation

Outdoor installation is possible up to -20 °C when the controller supply is not switched off. Installation must be protected from the effects of weather as much as possible, including protection from direct sunlight!

### 4.3 Installation location for agriculture

When using for animal keeping, do not install the device directly in the stable but in a separate room with a lower pollutant load. This helps to avoid damages caused by pollutant gases (e.g. ammonia fumes, hydrogen sulphide fumes).

### 4.4 Temperature influences during commissioning

Avoid condensation in the controller and functional faults attributable to condensation by storing the controller at room temperature!



## 5 Electrical installation

### 5.1 Safety precautions



#### Danger due to electric current

- Work on electric components may only be carried out by trained electricians or by persons instructed in electricity under the supervision of an electrician in accordance with electrical engineering regulations.
- The 5 electrical safety rules must be observed!
- It is forbidden to carry out work on electrically live parts.
- Other measures may be necessary to achieve safe electrical isolation.
- A second person must always be present when working on energized parts or lines who disconnects in case of emergency.
- Inspect electrical equipment periodically: retighten loose connections immediately replace damaged lines and cables.
- Always keep switch cabinets and all electrical supply facilities locked. Access is only allowed for authorized persons using a key or special tool.
- Operating the device with the housing cover removed is prohibited because energized, exposed parts are present inside the device. Disregarding this regulation can lead to severe personal injury.
- The required protective earth connection is established using screws between the housing parts in metal terminal space covers and housing casings. Commissioning is only permissible after these screws have been properly attached!
- The device owner is responsible for the EMC of the entire plant according to the locally applicable standards.
- Metal screwed-connections are not permitted in plastic housing parts because there is no potential equalization.
- Never clean electrical equipment with water or similar liquids.



#### Information

The respective connections are represented in the enclosure of this manual (@ Connection diagram)!

### 5.2 EMC-compatible installation of control lines

Pay attention to sufficient distance from powerlines and motor wires to prevent interferences. The control cable may not be longer than 30 m. Screened control cables must be used when the cable length is longer than 20 m. When using a shielded cable connect the shielding to one side only, i.e. only to the control unit with the protective ground (keep cable short and with as little inductance as possible!).

### 5.3 Mains connection

Power from the mains is connected to terminals: PE, L1 and N. Here, it must be strictly observed that the mains voltage lies within the allowable tolerance specifications ( Technical data and nameplate affixed to the side).



### Danger due to electric current

The mains voltage must comply with the DIN EN 50160 quality characteristics and the defined standard voltages in IEC 60038!



### 5.4 Signal input or sensor connection (E1, E2)

The unit has two analog inputs: Analog In 1 ="E1" and Analog In 2 = "E2" The connection is independent of the programmed operating mode and from the sensor signal employed.

- When connecting passive temperature sensorsTF.. (KTY81-210) or PT1000 at terminals "E1" and "T" or "E2" und "T" must be paid attention to no polarity.
   For a high interference immunity a capacitor must be connected directly to the sensor (1 nF parallel). With temperature sensors type TF.. (KTY81-210) a capacitor is integrated.
- When connecting **aktive** sensors at the terminals "E1" and "GND" or "E2" and "GND" attention must be paid to correct polarity, a 24 V DC power supply is integrated.
- For sensors in two-wire-technology (4 20 mA signal), the connection is made on the "E1" and "24 V" or "E2" and "24 V", "GND" terminal is omitted.



#### Danger due to electric current

Never apply line voltage to analog inputs!

### 5.5 Control outputs 0 - 10 V (A1, A2)

The analogue outputs can be used to activate a speed controller with 0 - 10 V input for example. Fans with integrated controller and 0 - 10 V input can be activated directly.

- Analog output 1 (terminals A1 GND)
- Controlled 0 10 V output for control circuit 1 (factory setting function 2A).
- Analog output 2 (terminals A2 GND)
  - For operation with one control circuit: constant voltage +10 V e.g. for supply of an external potentiometer (function factory setting 1 A).
  - For operation with a second control circuit: controlled 0 10 V output for control circuit 2 (function initial setting 8A).

Other functions can be assigned if necessary (@ Operating Instructions / IO Setup).



### Danger due to electric current

It is not permissible to connect outputs of several devices to each other!

### 5.6 Voltage supply for external devices (+24V, GND)

A voltage supply is integrated for external devices e.g. a sensor (max. current load P technical data). In case of overload or short circuit (24 V – GND), the external power supply is shut down (multi-fuse). The device performs a "Reset" and continues operation.

- It is not permissible to connect voltage outputs of several devices to each other!
- It is not permissible to connect voltage outputs in the device to each other!

### 5.7 Digital inputs (D1, D2)

Various functions can be allocated to the digital inputs "D1" and "D2" (IP IO Setup: Functions summary of the digital inputs). Activation via floating contacts (a low voltage of ca. 24 V DC is connected).



### Danger due to electric current

Never apply line voltage to the digital input! Observe input resistance and voltage range ( rechnical data).



### 5.8 Relay outputs (K1, K2)

Various functions can be allocated to the relay outputs "K1" and "K2" (@ IO Setup: function and inverting relais outputs). Max. contact rating @ technical data and connection diagram.

### Relays K1

- Connection of the floating contacts of relay "K1" to the terminals 11, 14, 12.
- "K1 Function" factory setting: <u>1K</u> = **Operating indication**. I.e. energized for operation without fault, for enable "OFF" de-energized.

### **Relays K2**

- Connection of the floating contacts of relay "K2" to the terminals 21, 24, 22.
- "K2 Function" factory setting: 2K = Fault indication. I.e. energized for operation without fault and for enable "OFF".

### 5.9 RS-485 interfaces for MODBUS RTU

The device has two RS-485 interfaces for networking via MODBUS RTU:

- 1. Interface "1A (1D+)", "1B (1D-)" for MODBUS Master applications
- Pre-programmed function is output from control circuit 1: <u>1. Control signal (2A)</u>
   e.g. for activating speed controllers for fans or fans with integrated controller and MODBUS interface (@ member MODBUS Master).
   The programmable functions correspond to the functions for the analogue outputs described in
- the IO Setup.
  Automatic addressing of members via a patented procedure.
  It is no longer necessary to address each individual member manually in the network. The "ID" connection is also assigned (for more information P the following chapter).
- Integrated fails afe wiring and 150  $\Omega$  termination.
- 2. Interface "2A (2D+)", "2B (2D-)" for MODBUS Slave applications
- Connection of the device to a superordinate building control system.
- Setting of address and communication parameters Programming: Menu group MODBUS Slave.



Connection MODBUS Slave and MODBUS Master interface

When using telephone flex with four cable cores, we recommend the following allocation:

- A (D+) = red
- B (D-) = black
- ID ID1/2 = yellow (for automatic addressing for MODBUS Master)
- GND = white



#### Information

- You must ensure correct connection; i.e. "A (D+)" must also be connected on the following devices to "A (D+)". The same applies to "A (D+)".
- Inaddition,a "GND" connection must be established, as dissimilar potential (over 10 V!) will lead to the destruction of the RS-485 interface (e.g. lightning).



- Except for the data link "A (D+)", "B (D-)", the "ID1 ID2" (automatic addressing for MODBUS Master) and the "GND" connection, no further cable cores of the data line may be used.
- Do not use wire shield!
- Pay attention to sufficient distance from powerlines and motor wires (min. 20 cm).

The data line must be connected from one device to the next. No other type of wiring is allowed! Always use only two wires of one lead (twisted pair) for the connection.

### MODBUS connection



#### Recommended wire types

- 1. CAT5 / CAT7 cables
- 2. J-Y (St) 2x2x0.6 (telephone wire)
- 3. AWG22 (2x2 twisted pair)

Max. allowed wire length 1000 m (CAT5/7 500 m)



### Information

If any matters are unclear, please contact our V-STE support department for control systems - ventilation technology. The information sheet "Network structure of MODBUS" R-TIL08\_01 contains detailed information about "MODBUS".

### 5.9.1 Addressing member MODBUS Master Interface

Up to 32 members can be connected at the MODBUS Master interface.

No other components are required for the patented automatic addressing (activation @ menu group MODBUS Master: AutoAddressing). Only the connections "ID1" and "ID2" of the Slave members are connected additionally next to the bus connection and at the "ID" connection of the MODBUS Master for this.

The "ID" connection of the MODBUS Master must be connected to the "ID1" or "ID2" connection of the **first Slave member**. This is recognised as a result and occupied by address **1**.

For the following users the connection "ID1" or "ID2" of a Slave user respectively is connected with connection "ID1" or "ID2" of the next Slave user.

The automatic addressing of other users is initiated by the previous user via this connection. The individual members can be addressed in advance without this device by an external terminal or a PC.

Alternatively, the addressing can be done manually by a separate hand held terminal or PC software, the appropriate number of members must then be entered on the MODBUS Master ( menu group MODBUS Master: BUS Slavecount).



### Information

- When using the automatic addressing, no repeaters can be used because these do not pass the signal through to the addressing.
- Depending on the version, the connections for MODBUS "A (D+)", "B (D-)" are available single or double at the Slave members. These are connected with each other internally electrically.
- The connections for the automatic addressing "ID1" and "ID2" are **not directly** connected with each other internally. These may not be bridged; any order of connection is possible.
- Do not connect the cable screen! When using the connection box, the cable screen of the CAT5 cable is connected internally by an RC element to "PE".
- The communication parameters are fixed @ Programming: Menu group MODBUS Master.



#### Networking with telephone wire



13.03.2013 v\_modbus\_master\_autoadr.vsd

The connection at the terminal is made at the terminals: 1A (1D+), 1B (1D-) and GND Connection of the users via the terminals: A (D+), B (D-), GND and ID1 / ID2

Networking with RJ45 patch cable by usage connection box for ECblue (part. no. 380085).



Connection to the MODBUS Master at the terminals: 1A (1D+), 1B (1D-), ID and GND Connection of the Slave members via the two RJ45 connections "BUS1" and "BUS2"



### 5.10 USB-interface

Over the USB interface if necessary a software update can be made. For this a consultation with the manufacturer is necessary.



#### Danger due to electric current

**Plug the jumper J1** to both PINs only for a software update via USB interface. The device will not switch on if this jumper is plugged to both PINs! Do not replug the jumper under voltage, observe the safety instructions!

### 5.11 Potential at control voltage connections

The control voltage connections (< 50 V) relate to the joint GND potential (Exception: Relay contacts are potential free). There is a potential separation between the control voltage connections and the protective earth. It must be ensured that the maximum external voltage at the control voltage connections cannot exceed 50 V (between "GND" terminals and "PE" protective earth). If necessary, a connection to the protective earth potential can be established, install bridge between "GND" terminal and the "PE" connection (terminal for screening).





## 6 Select operation mode

### 6.1 Mode and signal input



### Information

Simple installation is possible through the selection of the preprogrammed mode of operation ( Start-up)

This determines the basic function of the device; factory setting **1.01** = speed controller (activation via 0 - 10 V signal). The controller configuration is automatically carried out during selection of the application related mode of operation. The factory presets in accordance with the mode of operation are based on many years of experience, which is suitable for many applications. Under special circumstances, these can be individually adapted (@ Operating Instructions / Controller Setup: "Controller Configuration").

The purpose of the device is to reach and maintain the target values set. To accomplish this, the measured actual value (sensor value) is compared with the adjusted target value, and the controlled value (modulation) is deduced from this.

By selection of the mode the function for control circuit 1 is determined, this influences the following outputs (factory setting):

- 1. Analog output "A1" 0 10 V with function 2A ( Plectrical installation).
- 2. MODBUS Master interface "1A" + "1B" with function 2A ( Bectrical installation).

Mode	Signal or Sensor (input)	Function
1.01	Signal: 0 - 10 V, 0 - 20 mA, 4 - 20 mA	Speed controller with input for Setting signal, two step operation (Factory setting)
1.02	-	Manual speed controller with direct setting by the keys $\checkmark$ (0 - 100 % or in 1 - 5 steps)
2.01 *	Sensor KTY81-210 / PT1000 (E1)	Temperature control airconditioning and refrigeration (preset set-point 20.0 °C, P-band 5.0 K)
2.02 *	Sensor KTY81-210 / PT1000 (E1)	Temperature control depending on outdoor temperature (preset set-point 5.0 °C, - P-band 20.0 K)
2.03	Sensor KTY81-210 / PT1000 (E1)	Temperature control with additional functions (shutter and heating)
2.04 *	1x Sensor KTY81-210 / PT1000 (E1) 1x Sensor KTY81-210 / PT1000 (E2)	Temperature control with two sensors, comparison or average
2.05 *	1x Sensor KTY81-210 / PT1000 (E1) 1x Sensor KTY81-210 / PT1000 (E2)	Temperature control with two sensors differential temperature
3.01 *	Sensor MBG (E1)	Pressure control condensers (refrigeration)
3.02 *	Sensor MBG (E1)	Pressure control for condensers with input for refrigerant
3.03 *	1x sensor MBG (E1) 1x sensor MBG (E2)	Pressure control for two circuit condensers
3.04 *	1x sensor MBG (E1) 1x sensor MBG (E2)	Pressure control for two circuit condensers with input for refrigerant
4.01 *	Sensor DSG / MPG (E1)	Pressure control for ventilation systems
4.02	1x Sensor DSG / MPG (E1) 1x Sensor KTY81-210 / PT1000 (E2)	Pressure control depending on outdoor temperature
4.03	1x Sensor DSG / MPG (E1) 1x BUS RS 485	Pressure control with outdoor temperature-dependent setpoint adap- tation and activation by MODBUS
5.01 *	Sensor DSG / MPG (E1)	Volume control (constant) for ventilation systems
5.02	1x Sensor DSG / MPG (E1) 1x Sensor KTY81-210 / PT1000 (E2)	Volume control with setpoint depending on outdoor temperature
6.01 *	Sensor MAL (E1)	Air velocity control e.g. clean room

Operation with a second control circuit possible



#### Mode and Signal to E1, E2



#### 6.2 Operation with a second control circuit

The function for control circuit 1 is determined by selection of the mode. This influences the output with function  $\boxed{2A}$ .

A second control circuit with separate actual value measuring and separate output can be activated additionally if required.

Control circuit 2 influences the output with function 8A.

- Analog output "A2" (factory setting) IO Setup
- MODBUS Master interface @ member menu

Operation with a second control circuit is **not** possible in the following modes: **1.01**, **1.02**, **2.03**, **4.02**, **4.03**, **5.02** 

The following modes which are pre-programmed to operation with a second sensor can be reprogrammed to operation with a second control circuit.

### 2.04, 2.05, 3.03, 3.04

The second control circuit is activated by the "E2 function" for the second analogue input "E2" (@ menu group "Base Setup").



### E2 functions for activating control circuit 2:

		Factory setting		
E2 Function	Description second control circuit		2.Setpoint 1	
Temperature (8E)	Temperature control Presettings and sensor selection (@ Mode 2.01	TF	20.0 °C	
Cold-Pressure (9E)	Pressure control condensers Presettings and sensor selection @ Mode <b>3.01</b>	MBG0-30	15.00 bar	
Cold-Temperature (10E)	Pressure control for condensers with input for refrigerant Presettings, sensor selection and input for refrigerant @ Mode 3.02	MBG0-30	35.0°C	
Air Pressure (11E)	Pressure control Airconditioning Presettings and sensor selection @ Mode 4.01	DSG200	100.0 Pa	
Air flow (12E)	Air volume control Pressettings, sensor selection and K-Factor for inlet ring <i>F</i> Mode <b>5.01</b>	DSG200	44720 m <sup>3</sup> h	
Air speed (13E)	Air velocity control Presettings and sensor selection @ Mode 6.01	MAL1	0.50 m/s	

When activating control circuit 2, the "Setting" menu group is extended.

- The additional parameters for control circuit 2 are identified by a prefixed "2." e. g. "2.Setpoint 1".
- A prefixed "1." e. g. "1.Setpoint 1" is added to the parameters for control circuit 1.

### Example:Second control circuit Pressure control condensers

E2 function = 9E, Mo	de 2.01 for temperature control via control circuit 1
Setting	1.Setpoint 1
	Setpoint 1 for control circuit 1
20.0 °C	Setting range with passive sensor type "TF", "PT1000" : -50.0150.0 °C
1.Setpoint 1	Factory setting: 20.0 °C
Setting	1.Setpoint 2
	Setpoint 2 for control circuit 1
	Setting "Setpoint 2" e.g. reduced value for night operation.
1.Setpoint 2	Switch over Setpoint 1/2 by external contact (as long as no allocation is carried out
	──Display:
Setting	1. Pband 1
	Pband 1 for control circuit 1
5.0 K	Setting range with passive sensor type "TF", "PT1000": 0.0200.0 °C
1. Pband 1	Factory setting: 5.0 K
Setting	1. Min. Speed
	Minimal Speed for control circuit 1
0 %	Setting range: 0 rpm "1. Max. Speed"
1. Min. Speed	Factory setting: 0 %
Setting	1. Max. Speed
	Maximal Speed for control circuit 1
100 %	Setting range: 100 % "1. Min. Speed"
1. Max. Speed	Factory setting: 100 %
Setting	2.Setpoint 1
	Setpoint 2 for control circuit 2
12.0 bar	Setting range: in measuring range of sensor
2.Setpoint 1	Factory setting: 12,0 bar



Setting	2.Setpoint 2			
	Setpoint 2 for control circuit 2			
	Setting "Setpoint 2" e.g. reduced value for night operation.			
2.Setpoint 2	Switch over Setpoint 1/2 by external contact (as long as no allocation is carried out:			
	──Display:			
Setting	2. Pband 1			
	Pband 1 for control circuit 2			
5.0 bar	Setting range: in measuring range of sensor			
2. Pband 1	Factory setting: 5,0 bar			
Setting	2. Min. Speed			
	Minimal Speed for control circuit 2			
0 %	Setting range: 0. rpm "2. Max. Speed"			
2. Min. Speed	Factory setting: 0 %			
Setting	2. Max. Speed			
	Maximal Speed for control circuit 2			
100 %	Setting range: 100 % "2. Min. Speed"			
2. Max. Speed	Factory setting: 100 %			
Setting	Manual mode			
	Manual mode for control circuit 1			
OFF	"OFF" = automatic control as function of the set parameters (Factory setting)			
1. Manual mode	"ON" = automatic control without function, speed setting in menu "Speed manual"			
Setting	Speed manual			
	Speed Manual mode for control circuit 1			
100 %	Setting range: 0 rpm "1. Max. Speed"			
1. Speed man.	Factory setting: 100 %			

## Function extension for digital inputs "D1" and "D2" in operation with second control circuit

D1 / D2 Function	Description *
E1 / E2 (4D)	The output for control circuit 2 is set additionally to "A2" to "A1" (regardless of the programmed function for $\boxed{A1}$ ). Control circuit 1 has no output for the duration of the switching.
2. Setpoint 1/2 (9D)	for control circuit 2: Switch over "Setpoint 1" / "Setpoint 2"
2.Setp+Pband1/2 (16D)	for control circuit 2: Switch over Setpoint 1/2 and Pband 1/2 When programming this function, "Setting" additionally lists the parameter: "2.Pband 2 for control circuit 2."

\* Detailed description @ IO Setup / Digital Inputs "D1" / "D2"





### Following restrictions apply for the control circuit 2:

- The "Manual Mode" function in the "Setting" menu group only influences control circuit 1!
- The Limit (@ IO Setup 3D and Controller Setup) function influences both control circuits simultaneously.
- The "Max. Speed" setting by a digital input (P IO Setup 11D) simultaneously influences both control circuits. I.e. at "1.Max. Speed" and at "2.Max. Speed".
- The controller configurations (KP, KI, KD, TI @ Controller Setup) are identical for both control circuits. Fine adjustment is possible for each control circuit by the separate "Pband" setting.

### 6.3 External Setpoint / External speed setting in manual operation

External setpoint setting or external manual operation are possible using a 0 - 10 V (0 - 20 mA, 4 - 20 mA) signal at the "E2" and "GND" terminals. Configure "E2" in Base setup. For potentiometers, program Analog Out 1 (terminal "A1") to the function  $\boxed{1A} =$  "+10 V" (as factory setting  $\bigcirc$  IO Setup). E2 Analog In = factory setting 0 - 10 V



**External Setpoint** via external signal instead of "Setpoint 1". The "external Setpoint" function must be activated in base setup 1E for "E3 function". The active external Setpoint value is displayed in the "info" menu group. **External speed setting** in manual operation. The "external manual operation" function must be activated in the basic settings 2E for "E3 function". Switchover between settings on the device and external manual operation via the digital input (P IO Setup: "Control / manual operation" [7D]).

Not possible in modes with 2 sensors and operation with a second control circuit because the second analogue input is already occupied by it.

## 7 Start-up

### 7.1 Prerequisites for commissioning



### Attention!

- 1. You must mount and connect the device in accordance with the operating instructions.
- 2. Double check that all connections are correct.
- 3. The mains voltage must match the information on the rating plate.
- 4. Make sure that no persons or objects are in the fan's hazardous area.

### 7.2 Procedure for commissioning

- 1. Turn on mains voltage
  - Display:



(Function of display (P controls and menu)

- 2. Switch over between "Info" and "Main menu" with the "Esc" key combination
- 3. Menu group: Start



- Set the menu language if necessary (factory setting English = Language GB).
- The display can be switched between SI units (US units = OFF) and imperial (US) units (US units = ON).
- 4. Menu group: Base setup
- Set the desired mode (factory setting **1.01** = speed controller).
- Further settings depend on the selected mode and the sensor / setting signal used.
- 5. Menu group: Setting
- Set the parameters for the control mode.

#### Excerpt from the menu table

				Start					
Language	GB	GB	GB	GB	GB	GB	GB	GB	GB
US units	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF
		1	E	Base setu	р	1	1	1	1
Mode	1.01 1.02	2.01 2.03 2.04	2.02	2.05	3.01 3.02	3.03 3.04	4.01 4.02 4.03	5.01 5.02	6.01
E1 Analog In	1.01 = 0 - 10 V	TF	TF	TF	0-30 MBG	0-30 MBG	DSG200	4.01 = DSG200 4.02 + 4.03 = DSG50	0-1 MAL
Number steps	1.02 = 0								
Step 1 value	1.02 = (20%)								
E1 Refrigerant					3.02 = R503	3.04 = R503			
E1 K-Factor								75	
E2 Refrigerant						3.04 = R503			
		1	1	Setting	1	1	1	1	1
Set Intern1	1.01 = 80%								
Setting direct	1.02 = 80%								
Setting Step	1.02 = 0								
Setpoint1		20.0 °C	5.0 °C	0.0 °C	12.0 bar 35.0°C	12.0 bar 35.0°C	100 Pa	530 m <sup>3</sup> h	0.50 m/s
Pband 1		5.0 K	20.0 K	5.0 K	5.0 bar 7.0 K	5.0 bar 7.0 K	100 Pa	530 m <sup>3</sup> h	0.50 m/s
Set external1	1.01 = ON								



### Information

Adjust further settings according to the desired function (@ Operating Instructions / Programming)

## 8 Controls and Menu

## 8.1 Multipurpose LC display and keyboard



Α	Actual value display Display after line voltage is switched on or after the Esc key combination is used to exit the settings menu (display depends on selected mode and sensor value).	<ol> <li>Status bar</li> <li>Display of the menu group in which the displayed menu is located</li> <li>Display window</li> <li>Log entry which still was not seen</li> </ol>
В	Main menu Display after the Esc key combination is used to exit the actual value display. Select the desired menu group with the ▼▲ buttons and use the P-key to open it.	<ol> <li>5. Timer function active</li> <li>6. Fire-Symbol (heating operation)</li> <li>7. Moon-Symbol for set point 2</li> <li>8. Alarm symbol (fault message alternating with actual value display)</li> </ol>
Р	Program key and open menu.	9. Modulation control circuit 1
▼	Menu selection, reduce value.	10. Modulation control circuit 2 (if activated)
	Menu selection, increase value.	11. STOP-Symbol (enable)
▼ + ▲ Esc	<b>Esc</b> -key combination, Escape = leave menu. Switch between Info and Main menu.	<ol> <li>Position of the menu in the menu group</li> <li>List of the menu groups</li> </ol>



### 8.2 Menu operation

Info	Display after turning on the mains voltage	Main menu	
0 % Modulation	description for menu language English = "GB" (de- livery status). Switch over between "Info" * and "Main menu" with the <b>Esc</b> key combination.	Start Setting Protocol Base setup	
	Example for mode <b>1.01</b> (speed controller).	Controller Setup	
[ESC] Menu		[P] Enter	[ESC] Info
	*Info depending on device type: - "Speed" / rpm,- "Frequency" / Hz, - "Modulation" / %		

Main menu		
Start		
Setting		
Protocol		Select the desired menu group with the ▼ ▲ keys (text highlighted) and open with the P-
Base setup		ey.
Controller Setup		
[P] Enter	[ESC] Info	

### 

Start		
	PIN input	PIN input, e.g. for resetting to basic factory setting
[P] Edit	[ESC] Menu	

#### 

Start		
	GB Language	In the menu point "Language" display language can be selected. One returns to the menu group "Start" using the Esc ( $\mathbf{\nabla} + \mathbf{A}$ ) shortcut keys
[P] Edit	[ESC] Menu	

## 8.3 Example for programming mode **2.01** in "Base setup "





### 8.4 Menu structure



Menu dependent on mode

Selection of the menu group (e.g. Base setup) to the right through the ▼-key, to the left through the ▼-key.

You can go to the menu items in the menu groups (e.g. mode of operation) by using the **P** key. Use the arrow keys to move up and down within the menu group.

The menu groups consist of one area for the user (user menu) and one area for installation (service). The service area can be protected against unauthorized access by using a PIN.

In order to simplify the initial start-up operation, the service level is enabled at first (i.e., not protected by the PIN 0010 ( Operating Instructions / Controller Setup, PIN protection = OFF). If PIN protection is activated (ON), the service menu remains enabled after input of PIN 0010 as long as one is pressing keys. If no keys are pressed for ca. 15 minutes, the PIN is automatically erased, i.e. the service level is blocked.

To make adjustments, press the **P** key after selecting the menu item. If the previously set value starts to  $\bar{a}sh$ , it can be adjusted with the **V** +  $\blacktriangle$  keys and then saved with the **P** key. To exit the menu without making any changes, use the "Esc" short-key, i.e., the originally set values remain.



#### Information

After installation of the device has been carried out, PIN protection should be activated (@ Operating Instructions / Controller Setup)!



### 8.5 Overview menu groups

Main menu	Possible settings
Info	Display measured actual values, selected setpoints, modulation, etc.
	Settings cannot be made in this menu group.
	PIN input for reset to initial settings and to protect settings.
	Setting the menu language.
Start	Display in SI units or Imperial units (US)
	Complete re-start of the device.
	Display of the set mode, software version, etc.
Setting	Settings for Operation, Setpoint, Pband, Min. Speed, Max. Speed, etc.
Protocol	Display and query of events / malfunctions.
Dees setur	Setting of the desired mode, configuration of signal and sensor inputs.
Base setup	Activation control circuit 2.
	Activate set protection, save user settings.
Controllor Sofur	Activate alarm message in the event of a sensor fault.
Controller Setup	Activate limitation of modulation via digital input or timer of time switch.
	Configuration of control parameters, group control.
	Configuration and function assignment for: analogue outputs, digital inputs, relay out-
IO Setup	puts.
	Function MODBUS interface: COM2 for MODBUS Slave or MODEM SMS.
Limits	Limit messages depending on modulation, setting signal or sensor signal, offset to
	setpoint.
Timer	Integrated time switch with programmable timer functions.
	Clock fine adjustment
Diagnostic	Current operating states of the device.
MODBUS Slave MODBUS SMS	Addressing and configuration of the MODBUS Slave interface.
	alternatively
	Input of SIM PIN for MODBUS SMS interface (currently no function).
	Start automatic addressing of members.
MODBUS Master	alternatively
	Manual input of number of members.



## 9 Programming



### Display in SI units or Imperial units (US)

The following description is for display in SI units (factory setting). The appropriate conversion factors must be observed when switching over to Imperial units (US) (@ menu group Start / US Units).

### 9.1 Speed controller **1.01**, **1.02**

#### 9.1.1 Speed controller with setting by external signal **1.01**

Settings for controller output with function 2A (by analogue signal @ IO Setup, by MODBUS @ members menu).

Main menu	Base setup
Setting	
Protocol	
Base setup	
Controller Setup	
IO Setup	
Base setup	Mode
	Factory setting Mode: 1.01
1.01	
Mode	
Base setup	E1 Analog In
	Selection: 0 - 10V, 0 - 20 mA, 4 - 20 mA (Inverting, E1 BUS Modus @ IO Setup)
0 - 10V	Factory setting: 0 - 10 V
E1 Analog In	
Base setup	E2 Function (only for special applications)
	Analog input 2 "E2" factory set at "OFF".
OFF	
E2 Function	For operation with a second setting signal and switch over by potential-free contact: E2 Function = Ext. Setpoint (1E)
	Necessary function for digital input: E1/E2 (4D) @ IO Setup
	For operation with a second signal and automatic control at the higher level: E2 Function = comparison E1 (4E).
Base setup	E2 Analog In
	Display as long as no function allocated:
	Selection: 0 - 10 V, 0 - 20 mA, 4 - 20 mA (Inverting, E2 BUS Modus @ IO Setup)
E2 Analog In	Factory setting: 0 - 10 V

### Base setup 1.01



### Setting for operation 1.01

Main menu	Setting
Setting	
Protocol	
Base setup	
Controller Setup	
IO Setup	
Setting	Set Intern1
	Setting range manual speed setting: 0100 % ≙ "Min. Speed" "Max. Speed"
80 %	Factory setting: 80 %
Set Intern1	
Setting	Set Intern2
	Setting "Set Intern2" e.g. reduced value for night operation.
	Switch over Interni 1/2 over external contact (display where no allocation:
Set Intern2	IO Setup).
Setting	Min. Speed
	Setting range: 0 "Max. Speed"
0 %	Factory setting: 0 %
Min. Speed	
Setting	Max. Speed
	Setting range: 100 % "Min. Speed"
100 %	Factory setting: 100 %
Max. Speed	
Setting	Set external1
	"ON" (factory setting) = speed setting by external Signal
ON	"OFF" = Setting "Set Intern1"
Set external1	

Diagram setting signal and output voltage (Idealized principle diagram)



MODBUS Out: speed setting over MODBUS Analog Out: speed setting over analog output 0 - 10 V Si Signal



### 9.1.2 Speed controller with direct setting by keyboard 1.02

Main menu	Base setup
Sotting	
Protocol	
Piolocoi Raco cotun	
Controller Setup	
Controller Setup	
IO Setup	
Base setup	Mode
	Mode selection: 1.02
1.02	
Mode	
Base setup	Number steps
	Selection: 0, 1, 2, 3, 4, 5
0	Factory setting: 0
Number steps	
•	Number steps: 0
	In the factory setting "0" (without steps) the modulation can be set directly with the ▼ ▲ keys (☞ setting in operation).
	Number steps: 1, 2, 3, 4, 5
	The modulation value can be assigned to each step. The desired step is set with the ▼ ▲ keys (☞ setting in operation).
	The following menus become active depending on the selected step count. (Step not active = $[]$ )
Base setup	Step 1 value - 5
	Setting range: 0100 %.
	Factory setting: (Number steps 0)
Step 1 value	Factory setting: 20 %, 40 %, 50 %, 60 %, 100 % (Number steps 1 - 5)

### Base setup 1.02

### Menu group "Setting" (only when needed)

Main menu Setting Protocol Base setup Controller Setup IO Setup	Setting
Setting 80 % Setting direct	Setting direct (at Number steps: 0 ☞ "Base setup") If the setting is to be made during operation directly with the ▼ ▲ keys, no setting is necessary here (☞ setting in operation 1.02). Setting range: Min. Speed - Max. Speed Factory setting: 80 %
0 Setting Step	Setting step (at Number steps: 1 - 5 ☞ "Base setup") If the setting is to be made during operation directly with the ▼ ▲ keys, no setting is necessary here (☞ setting in operation 1.02). Setting range: 0 - setting nummber steps Factory setting: 0





Setting	Min. Speed
	Setting range: 0 "Max. Speed"
0 %	Factory setting: 0 %
Min. Speed	
Setting	Max. Speed
	Setting range: 100 % - "Min. Speed"
100 %	Factory setting: 100 %
Max. Speed	

### Setting in operation 1.02

After installation is completed, only the <b>"Setting direct"</b> or <b>"Setting Step"</b> setting is visible in the "Info" menu group. All other menus are protected by a PIN.		
Info	Setting direct (at Number steps: 0 @ "Base setup")	
76 % Setting direct	Setting range: Min. Speed - Max. Speed Factory setting: 80 %	
	The value set by the $\checkmark$ keys is accepted and executed directly ( <b>P</b> key without function).	
Info	Setting step (at Number steps: 1 - 5 @ "Base setup")	
5 Setting Step	Setting range: 0 - programmed number steps Factory setting: 0	

Switching over to the protected "Info" menu group takes place automatically after approximately 15 minutes if no key is pressed.

#### Possibilities for early activation of PIN protection:

- Select the "Info" menu group and confirm with the **P** key.
- Press the Esc key combination several times until the "Setting direct" or "Setting Step" menu is displayed.
- Execute the "Reset" function in the "Start" menu group.
- By switching the mains voltage off and then on again.

### Input PIN 0010 to exit the protected area





## 9.2 Temperature control 2.01...2.05

### 9.2.1 Basic setting 2.01... 2.05

Main menu	Base setup
Setting	
Protocol	
Base setup	
Controller Setup	
IO Setup	
•	
Base setup	Mode
	Mode selection e.g. 2.01
2.01	
Mode	
Base setup	E1 Analog In
	The sensor input is factory set in modes of group 2 to sensors of the "TF" type series
TF	(sensor type KTY81-210).
E1 Analog In	Measuring range: -50.0+150 °C
	Connection terminals: "GW E1 Viive" and "T"
	Other settable sensors:
	• $PT1000$ at terminals "E1" and "T" (measuring range -50.0 +150 °C)
	<ul> <li>MTC-120V (type designation for active sensor with 0 - 10 V output, connection to</li> </ul>
	terminals "E1". "GND" and "24 V". measuring range: -10+120 °C)
	• 0 - 10 V. 0 - 20 mA. 4 - 20 mA (for sensors with free measuring range and linear
	characteristic)
	The sensor measuring range must be entered for sensors with free measuring range in order to display the actual value correctly.
	Example with a 0 - 10 V sensor and 0 - 100 °C measurement range:
	E1 Analog In = 0 - 10 V, E1 Unit = °C, E1 Decimals = 1, E1 Min. = 0,0 °C, E1 Max. =
	100,0 °C,
	When selecting sensors with active signal, the setpoint and the Pband are automati-
	cally set to the 1/2 measuring range.
Base setup	E1 Offset
	Sensor calibration with calibrated comparison device.
20.0 °C	The current "E1 Actual" is displayed including the offset set here.
E1 Offset	



Base setup	E2 Function
	The second signal input is not activated at the factory for modes with one sensor.
OFF	The function is automatically jointly programmed in operating modes using two sen-
E2 Function	<ul> <li>sors. The second analog input is thus allocated and additional function allocations are not possible.</li> <li>2.04 F2 Function at 4F1 preprogrammed = comparison value with control to allocated and additional function allocations are allocated and additional function allocations are not possible.</li> </ul>
	higher temperature. Alternative: average of 2 measuring points for this must be reprogrammed on function [3E] preprogrammed sensor type "TF".
	<ul> <li>2.05 E2 Function at <u>5E</u> preprogrammed = regulation on difference temperature between sensor 1 and sensor 2. Preprogrammed sensor type "TF".</li> </ul>
	Adjustable "E2 Function"
	<ul> <li>IE = External Setpoint e.g. via external signal (0 - 10 V) instead of "Setpoint 1"</li> <li>For sensor type "E1 Analog In" = "TF or PT1000": 0 - 10 V ≙ -50.0+150 °C.</li> </ul>
	<ul> <li>For sensors with active signal: 0 - 10 V ≅ 0 - 100 % sensor measuring range.</li> <li>[2E] = External manual operation via external signal (0 - 10 V). Switch over</li> </ul>
	between settings on the device and external manual operation via digital input ( IO Setup: function 7D).
	• [6E] = sensor for outdoor temperature-dependent setpoint adaptation (at <b>2.03</b> not possible), pre-programmed sensor type "TF".
	<ul> <li>additional parameters menu group "Setting": T-Band, T-Start SA, Min. Setpoint.</li> <li>additional parameters menu group "Info": Setpoint Control</li> </ul>
	<ul> <li>Example P Setting for operation 4.01 4.03 / additional menu items.</li> </ul>
	<ul> <li>[7E] = Measurement value = Measurement value e.g. for limit indication, display in Info menu "E2 Actual".</li> </ul>
	• 8E 13E = sensor input for control circuit 2 (at 2.03 not possible)  base setup / operation with second control circuit.

### 9.2.2 Settings for operation modes 2.01... 2.05

2.01	Temperature control airconditioning and refrigeration (preset set-point 20.0 °C, P-band 5.0 K)
2.02	Temperature control depending on outdoor temperature (preset set-point 5.0 °C, - P-band 20.0 K)
2.03	Temperature control with pre-programmed additional functions (heating, shutter, temperature monitor- ing).
2.04	Temperature control with 2 sensors Comparison with control to higher value "E2 Function" set to comparison 4E. Display during operation: "Control value " Alternative: Average calculation of 2 measuring places "E2 Function" set to 3E. Display during
2.05	Temperature control with 2 sensors, regulation on difference temperature. Display during operation: "Value of E1 - E2" in K, "E1" = reference temperatur, "E2" causes positiv (E2 < E1) or negative (E2 > E 1) difference.

Settings for controller output with function [2A] (by analogue signal @ IO Setup, by MODBUS @ members menu).

Main menu	Setting	
Setting		
Protocol		
Base setup		
Controller Setup		
IO Setup		



Setting	Setpoint1
	Setting range with passive sensor type "TF", "PT1000": -50.0150.0 °C
20.0 °C	Factory setting: 2.01, 2.03, 2.04 : 20.0 °C
Setpoint1	at <b>2.02</b> : 5.0 °C
	at <mark>2.05</mark> : 0.0 °C
	Setting range with passive sensor type "MTG-120V": -10.0 °C+120.0 °C
	Factory setting 2.01 - 2.05 : 55.0 °C
Setting	Setpoint2
County	Setting "Setpoint 2" e.g. reduced value for night operation
	Switch over Setpoint 1/2 by external contact (display as long as no allocation is carried
Cotracint2	out: @ IO Setup).
Setpointz	
Setting	Pband
	Narrow control range = Short control times
5.0 K	Wide control range = Longer control times and more stable control
Pband	
	Passive sensor type "TF", "PT1000"
	Setting range: 0 - 200.0 K (Kelvin)
	Factory setting: 5.0 K, (at <b>2.02</b> : 20.0 K)
	, , , , ,
	active Sensor type "MTG-120V"
	Setting range: -120.0+120.0 K
	Factory setting: 65.0 K
Setting	Min Sneed
Oetting	Setting range: 0 "Max Speed"
0.0/	Eactory setting: 0 %
0 %	ractory setting. 0 70
Min. Speed	
Setting	Max. Speed
	Setting range: 100 % "Min. Speed"
100 %	Factory setting: 100 %
Max. Speed	
Setting	Manual mode
	"OFF" = automatic control as function of the set parameters (Factory setting)
OFF	"ON" = automatic control without function, speed setting in menu "Speed manual"
Manual mode	
	—
Setting	Speed manual
	Manual speed setting without influence by the external signal.
100 %	Activation by menu "Manual mode" or external contact at digital input ( PIO Setup).
Speed manual	Setting range: 0100 % ≙ "Min. Speed" "Max. Speed"
	Factory setting: 100 %
	For information about deactivated regulation the adjusted value for manual speed is indicated alternating with the actual value.



#### 9.2.3 Functional diagrams temperature control

Example 1: Temperature control in factory setting "Cooling function" (Idealized principle diagram)



(Controller Setup: "Actual>Nominal=n+" at "ON") MODBUS Out: speed setting over MODBUS Analog Out: speed setting over analog output 0 - 10 V S Setpoint R Pband

I Actual value

Example 2: Temperature control in "Heating function" (Idealized principle diagram)



(Controller Setup: "Val>Set=n+" to "OFF") MODBUS Out: speed setting over MODBUS Analog Out: speed setting over analog output 0 - 10 V

S Setpoint

R Pband

I Actual value



### 9.2.4 Additionally for 2.03 (controller output 2 with function 6A)

The 0 - 10 V output signal A2 can, e.g., be used for triggering a shutter or heating.

Setting	Offset AnalogOut
	The target value for this output is the target value (Setpoint) for the ventilation "offset"
0.0 K	setting.
Offset AnalogOut	Adjustment: range +/- 10,0 K relative to the active Setpoint.
	Example for triggering a shutter servomotor:
	At factory setting "0,0 K" = synchronous operation.
	The analog output is factory set to increasing activation during increasing temperature. Reprogramming to "Heating function", i.e., increasing modulation during decreasing temperature is possible (@PIO Setup).
Setting	Pband AnalogOut
	Pband AnalogOut = separately adjustable range of control (P-band) for 0 - 10 V output
2.0 K	Setting range: 0200.0 K
Pband AnalogOut	Factory setting: 2.0 K
Setting	Min. AnalogOut
	Min. AnalogOut = Minimal output voltage
0 %	Setting range: 0100 % = 0 - 10 V
Min. AnalogOut	Factory setting: 0 %
Setting	Max. AnalogOut
	Max. AnalogOut = Maximal output voltage
100 %	Setting range: 1000 % = 10 - 0 V
Max. AnalogOut	Factory setting: 100 %

Example for signal out 0 - 10 V (IO Setup: "A2 function" = 6A)



Example: Setpoint ventilation 25.0°C, Offset -5.0 K, Pband 10.0 K S Setpoint Ventilation +/- Offset

R Pband

I Actual value



#### 9.2.5 For mode 2.03: Relay output for Heating or Cooling

Setting	OffsetDigitalOut
	Offset Digital Out = Offset for relay output ("K2" is pre-programmed by the factory).
-1.0 K	The relay operating point deviates by the adjusted offset of the Setpoint of the ventila-
OffsetDigitalOut	tion (if relay "K2" not inverted, terminal "21"-"24" bridged).
	Setting range: -10.0+10.0 K
	Factory setting: -1.0 K
	<ul> <li>"0.0 K" set, i.e. heating "ON" when: actual value = Setpoint</li> </ul>
	• During negative offset value heating "ON" when: actual value = Setpoint - offset
	• During positive offset value heating "ON" when: actual value = Setpoint + offset
Setting	Hyst.DigitalOut
	Switching hysteresis of the relay
1.0 K	Setting range: 010,0 K, Factory setting: 1.0 K (Kelvin)
Hyst.DigitalOut	

### Temperature variation with factory setting [9K] in IO Setup e. g. for controlling a Heating.

If the ambient temperature is lower than the set operating point, the heating remains switched on. If the ambient temperature exceeds the set operating point of the heating by 2 K (Kelvin), the heating is switched off. I.e., the release point is situated at the hysteresis value over the operating point.





### Temperature variation with reprogramming to 10K for "K2" in IO Setup, e.g., for activation of the Cooling

Example:



If the ambient temperature is higher than the set operating point, the cooling remains switched on. If the ambient temperature falls below the set operating point of the cooling by 2 K (Kelvin), it is switched off. I.e., the OFF point is situated at the hysteresis value under the ON point.





### 9.2.6 For mode 2.03 Relay output for temperature monitoring

If the set value for the "minimum alarm" is not reached or the set value for the "maximum alarm" is exceeded, a message is generated via the alarm symbol in the display. In addition, "Lmt E1 min" is displayed alternately with the actual value for the minimum alarm and Lmt E1 max for the "Maximum alarm". An external message follows via the factory-assigned"K1" relay. (IO Setup: K1 function = [2K]).

Setting	Alarm Minimum
	Setting range: OFF / -49.9150.0 °C
0.0 °C	Factory setting: 0.0 °C
Alarm Minimum	
Setting	Alarm Maximum
	Setting range: OFF / -49.9150.0 °C
40.0 °C	Factory setting: 40.0 °C
Alarm Maximum	

Info	Example for display if falling below setting "Alarm Minimum" alternating to the actual value display. Relay "K1" disengages (if not inverted).
Info	Example for display if exceeding setting "Alarm Maximum" alternating to the actual value display
Lmt E1 max.	Relay "K1" disengages (if not inverted).


# 9.3 Pressure control for condensers refrigeration 3.01...3.04

# 9.3.1 Base setup 3.01 ... 3.04

Main menu	Base setup
Start	
Setting	
Protocol	
Base setup	
Controller Setup	
	-
Base setup	Mode Mode selection e.g. 3.01
3.01 Mode	
Base setup	E1 Analog In
•	The sensor input is factory set for modes of group <b>3</b> to sensor type "MBG-30I ".
MBG0-30	Measuring range: 030 bar
E1 Analog In	Output signal: 4 - 20 mA
	Connection terminals: "E1", "24V"
	<ul> <li>Other settable sensors:</li> <li>MBG-50I (measuring range 050 bar, output signal 4 - 20 mA)</li> <li>DSF2-25 (measuring range 225 bar, output signal 4 - 20 mA)</li> <li>0 - 10 V, 0 - 20 mA, 4 - 20 mA (for sensors with free measuring range and linear characteristic)</li> <li>The sensor measuring range must be entered for sensors with free measuring range in order to display the actual value correctly.</li> <li>Example 0 - 10 V sensor and measuring range 0 - 20 bar:</li> <li>E1 Analog In = 0 - 10 V, E1 Unit = bar, E1 Decimals = 1, E1 Min. = 0,0 bar, E1 Max. =</li> </ul>
	20,0 bar
Base setup	E1 Offset
	Sensor calibration with calibrated comparison device.
0.00 bar	The current "E1 Actual" is displayed including the offset set here.
E1 Offset	_
Base setup	E1 Refrigerant
R503 E1 Refrigerant	With <b>3.02</b> and <b>3.04</b> operating modes with input of the refrigerant, the device automatically calculates the corresponding temperature for the measured pressure. The settings for offset, target value and the controlling range are then carried out in °C or K. Calculation for relative pressure (differential measurement of pressure relative to ambient pressure). No further settings are necessary for pressure sensors model e.g.
	sensors with other measurement ranges, the "E1 Min. value" and the "E1 Max. Value". Setting in "bar" although unit display is in "°C"!





Base setup	E2 Function
OFF E2 Function	The second signal input is not activated at the factory for modes with one sensor. The function is automatically jointly programmed in operating modes using 2 sensors. The second analog input is thus allocated and additional function allocations are not possible.
	<ul> <li>Modes with two sensors</li> <li>3.03 and 3.04 E2 Function at 4E preprogrammed = comparison value with control to higher value (two circuit condensers).</li> </ul>
	Adjustable "E2 Function"
	<ul> <li>IE = external setpoint e.g. by external signal (0 - 10 V) instead of setting "Setpoint 1". 0 - 10 V ≙ 0 - 100 % sensor measuring range.</li> </ul>
	<ul> <li><u>2E</u> = External manual operation via external signal (0 - 10 V). Switch over between settings on the device and external manual operation via digital input ( IO Setup: function 7D).</li> </ul>
	• <u>3E</u> = Sensor average to E1
	• <u>5E</u> = Sensor difference to E1
	<ul> <li>[6E] = sensor for outdoor temperature-dependent setpoint adaptation, pre- programmed sensor type "TF".</li> </ul>
	<ul> <li>Menu group "Setting" additional parameter: T-Band, T-Start SA, Min. Setpoint.</li> <li>Menu group "Info" additional parameter: Setpoint control</li> </ul>
	<ul> <li>Example P Setting for operation 4.01 4.03 / additional menu items.</li> </ul>
	<ul> <li>[7E] = Measurement value = Measurement value e.g. for limit indication, display in Info menu "E2 Actual".</li> </ul>
	• [8E] [13E] = sensor input for control circuit 2 (38) base setup / operation with second control circuit.

Selection of the refrigerants:								
R12	R13	R13b1	R22	R23	R32	R114	R134a	R142B
R227	R401	R401A	R401B	R402	R402A	R402B	R404A	R407A
R407B	R407C	R410A	R500	R502	R503	R507	R717	

## 9.3.2 Setting for operation modes 3.01... 3.04

- 3.01 Pressure control condensers, setting Setpoint in bar
- 3.02 Pressure control for condensers with input for refrigerant, Setpoint in °C
- **3.03** Two sensors for dual circuit condenser. Automatic regulation to the highest pressure (selection amplifier integrated) operation display: "Control value", Setpoint in bar
- **3.04** Two sensors for dual circuit condenser with input for refrigerant automatic regulation to the highest pressure (selection amplifier). Setpoint in °C , also for different refrigerants suitably there comparison of the temperatures. Display during operation: "Control value "

Settings for controller output with function 2A (by analogue signal @ IO Setup, by MODBUS @ members menu).

Main menu	Setting
Start	
Setting	
Protocol	
Base setup	
Controller Setup	
Setting	Setpoint1
	3.01 and 3.03
12.0 bar	Setting range: in measuring range of sensor
Setpoint1	Factory setting: 12.0 bar
	<b>3.02</b> and <b>3.04</b>
	Setting range: dependent on the selected refrigerant
	Factory setting: 35.0 °C





Setting	Setpoint2
	Setting "Setpoint 2" e.g. reduced value for night operation.
	Switch over Setpoint 1/2 by external contact (display as long as no allocation is carried
Setpoint2	out: []@ IO Setup).
Setting	Pband
	Narrow control range = Short control times
5.00 bar	Wide control range = Longer control times and more stable control
Pband	3.01 and 3.03
	Setting range: in measuring range of sensor
	Factory setting: 5.0 bar
	3.02 and 3.04
	Setting range: dependent on the selected refrigerant
	Factory setting: 7.0 K
Setting	Min. Speed
	Setting range: 0 "Max. Speed"
0 %	Factory setting: 0 %
Min. Speed	
Setting	Max. Speed
	Setting range: 100 % "Min. Speed"
100 %	Factory setting: 100 %
Max. Speed	
•	
Setting	Manual mode
	"OFF" = automatic control as function of the set parameters (Factory setting)
OFF	"ON" = automatic control without function, speed setting in menu "Speed manual"
Manual mode	
Setting	Speed manual
	Manual speed setting without influence by the external signal.
100 %	Activation by menu "Manual mode" or external contact at digital input ( P IO Setup).
Speed manual	Setting range: 0100 % ≙ "Min. Speed" "Max. Speed"
	Factory setting: 100 %
	For information about deactivated regulation the adjusted value for manual speed is
	indicated alternating with the actual value.



#### **9.3.3** Functional diagrams pressure control condensers Functional diagram for Mode **3.01** and **3.03** (Idealized principle diagram)



MODBUS Out: speed setting over MODBUS Analog Out: speed setting over analog output 0 - 10 V S Setpoint

S Setpoir R Pband

I Actual value

I Actual value

Functional diagram for Mode **3.02** and **3.04** (Idealized principle diagram)



MODBUS Out: speed setting over MODBUS Analog Out: speed setting over analog output 0 - 10 V S Setpoint R Pband

I Actual value



Information The factory default presets must be adapted to match the system conditions by a competent person.

# 9.4 Pressure control airconditioning **4.01**... **4.03**

# 9.4.1 Base setup 4.01... 4.03

Main menu	Base setup
Start	
Setting	
Protocol	
Base setup	
Controller Setup	
Base setup	Mode
	Mode selection e.g. <b>4.01</b>
4.01	
Mode	
Base setup	E1 Analog In
	The sensor input is factory set for modes of group 4 to sensor type "DSG200 ".
DSG200	Measuring range: 0200 Pa
E1 Analog In	Output signal: 0 - 10 V
	Connection terminals: "E1", "GND", "24V"
	<ul> <li>Other settable sensors / measuring ranges:</li> <li>"DSG 50", "DSG100", "DSG200", "DSG300", "DSG500", "DSG1000", "DSG2000", "DSG4000", "DSG6000", INT300, INT500 (numerical data ≙ measuring range [Pa], output signal 0 - 10 V). Type designation DSG ≙ pressure sensor with new type designation MPG</li> <li>0 - 10 V, 0 - 20 mA, 4 - 20 mA (for sensors with free measuring range and linear characteristic)</li> <li>The sensor measuring range must be entered for sensors with free measuring range in order to display the actual value correctly.</li> <li>Example with a 0 - 10 V sensor and 0 - 400 Pa measurement range:</li> <li>E1 Analog In = 0 - 10 V, E1 Unit = Pa, E1 Decimals = 1, E1 Min. = 0,0 Pa, E1 Max. = 400 Pa</li> </ul>
Base setup	E1 Offset
	Sensor calibration with calibrated comparison device.
0.0 Pa	The current "E1 Actual" is displayed including the offset set here.
E1 Offset	_



Base setup	E2 Function
	The second signal input is not activated at the factory for modes with one sensor.
OFF	The function is automatically jointly programmed in operating modes using two sen-
E2 Function	sors. The second analog input is thus allocated and additional function allocations are not possible.
	Modes with two sensors
	<ul> <li>For 4.02 E2 Function at 6E preprogrammed = sensor for setpoint lowering. Preprogrammed sensor type "TF"</li> </ul>
	<ul> <li>For 4.03 E2 Function at 6E preprogrammed = sensor for setpoint lowering.</li> <li>Preprogrammed sensor: type "0 - 10 V" (measuring range -35.0+65.0 °C</li> </ul>
	Pre-programmed in the IO setup:
	<ul> <li>To read out the sensor value via bus: E2 Busmode = "ON"</li> <li>For eaching via busy D1 Eventing = [4D]</li> <li>D4 Event at a "ON"</li> </ul>
	<ul> <li>For enabling via bus. D1 Function = [1D], D1 Busmode = 'ON'</li> <li>For switch over setpoint 1 /2 via Bus: D2 Function = [5D], D2 Busmode = "ON"</li> </ul>
	Adjustable "E2 function" for modes with one sensor
	<ul> <li>IE = external setpoint e.g. by external signal (0 - 10 V) instead of setting "Setpoint 1". 0 - 10 V ≜ 0 - 100 % sensor measuring range.</li> </ul>
	• 2E = External manual operation via external signal (0 - 10 V). Switch over
	IO Setup: function [7D]).
	• 3E = Sensor average to E1
	• 4E = Sensor comparison to E1
	• 5E = Sensor difference to E1
	<ul> <li>TE = Measurement value = Measurement value e.g. for limit indication, display in Info menu "E2 Actual".</li> </ul>
	<ul> <li><u>8E</u> <u>13E</u> = sensor input for control circuit 2 <sup>(2)</sup> base setup / operation with second control circuit.</li> </ul>

### 9.4.2 Setting for operation modes 4.01... 4.03



Pressure control, Setting Setpoint in Pa

Pressure control setpoint depending on outdoor temperature

**4.03** Pressure control with outdoor temperature-dependent setpoint adaptation and activation by MODBUS

Settings for controller output with function 2A (by analogue signal @ IO Setup, by MODBUS @ members menu).

Main menu	Setting
Start	
Setting	
Protocol	
Base setup	
Controller Setup	
Setting	Setpoint1
	Setting range: in measuring range of sensor
100 Pa	Factory setting: 100 Pa
Setpoint1	
Setting	Setpoint2
	Setting "Setpoint 2" e.g. reduced value for night operation.
	Switch over Setpoint 1/2 by external contact (display as long as no allocation is carried
Setpoint2	out: []@ IO Setup).



Setting	Pband
	Narrow control range = Short control times
100 Pa	Wide control range = Longer control times and more stable control
Pband	Setting range: in measuring range of sensor
	Factory setting: 100 Pa
Setting	Min. Speed
	Setting range: 0 "Max. Speed"
0 %	Factory setting: 0 %
Min. Speed	
Setting	Max. Speed
	Setting range: 100 % "Min. Speed"
100 %	Factory setting: 100 %
Max. Speed	
Setting	Manual mode
	"OFF" = automatic control as function of the set parameters (Factory setting)
OFF	"ON" = automatic control without function, speed setting in menu "Speed manual"
Manual mode	
Setting	Speed manual
	Manual speed setting without influence by the external signal.
100 %	Activation by menu "Manual mode" or external contact at digital input ( PIO Setup).
Speed manual	Setting range: 0100 % ≙ "Min. Speed" "Max. Speed"
	Factory setting: 100 %
	For information about deactivated regulation the adjusted value for manual speed is indicated alternating with the actual value.

### Additional menu item for mode **4.02** and **4.03** with outside-temperature dependent targetsetpoint.

Outside-temperature dependent target-setpoint



An outside temperature compensation can be activated (sensor connection "E2" = "Analog In 2") when being operated as a pressure regulation device.

An optimal building climate, e.g., can be achieved through this. Through this function, the set and active "Setpoint1" or "Setpoint2" is automatically changed proportional to the measured outside temperature (IPP Info: "Setpoint control").

S1 S	Setpoint1
S2 S	Setpoint2
P-min	Min. Setpoir
T-min	Min. tempera
T 04-	4 O - 4

P-min. Min. Setpoint T-min Min. temperature T-Start Setpoint reducing will start below this outside temperature T-band Temperature range AT Outdoor temperature

Setting	T-Band SA
	Temperature range in which the setpoint change continiously with outside temperature
30 K	Setting range: 0.0100.0 K
T-Band SA	Factory setting: 30.0 K



Setting	T-Start SA
	Setpoint reducing will start below this outside temperature
15 °C	Setting range: -10.040.0 °C
T-Start SA	Factory setting: 15.0 °C
Setting	Min. Setpoint
	Minimum pressure for very low outside temperature
70.0 Pa	Setting range: in measuring range of sensor
Min. Setpoint	Factory setting: 70 Pa

# 9.5 Volume control 5.01 and 5.02

# 9.5.1 Basic setting 5.01 and 5.02

Main menu	Base setup
Start	
Setting	
Protocol	
Base setup	
Controller Setup	
Base setup	Mode
	Mode selection e.g. 5.01
5.01 Mode	
Base setup	E1 Analog In
DSG200 E1 Analog In	The sensor input is factory set for modes of group <b>5</b> to sensor type "DSG200". Measuring range: 0200 Pa Output signal: 0 - 10 V Connection terminals: "E1", "GND", "24V"
	<ul> <li>Other settable sensors / measuring ranges:</li> <li>"DSG 50", "DSG100", "DSG200", "DSG300", "DSG500", "DSG1000", "DSG2000", "DSG4000", "DSG6000", INT300, INT500 (numerical data ≙ measuring range [Pa], output signal 0 - 10 V). Type designation DSG ≙ pressure sensor with new type designation MPG</li> <li>0 - 10 V, 0 - 20 mA, 4 - 20 mA (for sensors with free measuring range and linear characteristic)</li> </ul>
	The sensor measuring range must be entered for sensors with free measuring range in order to display the actual value correctly. Example with a 0 - 10 V sensor and 0 - 400 Pa measurement range: E1 Analog In = 0 - 10 V, E1 Min. = 0,0 Pa, E1 Max. = 400 Pa
Base setup	K Factor
75 E1 K-Factor	Input of the "K factor" dependent on the fan (inlet duct). setting range: 05000 Factory setting: 75
Base setup	E1 Offset
0.0 Pa E1 Offset	Sensor calibration with calibrated comparison device.



Base setup	E2 Function
	The second signal input is not activated at the factory for modes with one sensor.
OFF	The function is automatically jointly programmed in operating modes using two sen-
E2 Function	sors. The second analog input is thus allocated and additional function allocations are not possible.
	Modes with two sensors
	• For <b>4.02</b> E2 Function at <u>6E</u> preprogrammed = sensor for setpoint lowering. Preprogrammed sensor type "TF "
Adjustable "E2 function" for modes with one sensor • $\boxed{1E}$ = external setpoint e.g. by external signal (0 - 10 V) ins $1$ " 0 = 10 V $\stackrel{\triangle}{\rightarrow}$ 0 = 100 % setting range	Adjustable "E2 function" for modes with one sensor
	<ul> <li>IE = external setpoint e.g. by external signal (0 - 10 V) instead of setting "Setpoint 1". 0 - 10 V ≜ 0 - 100 % setting range.</li> </ul>
	• [2E] = External manual operation via external signal (0 - 10 V). Switch over
	between settings on the device and external manual operation via digital input (
	[3E] = Sensor average to E1
	• 4E = Sensor comparison to E1
	5E = Sensor difference to E1
	<ul> <li>[7E] = Measurement value = Measurement value e.g. for limit indication, display in Info menu "E2 Actual".</li> </ul>
	<ul> <li>[8E] [13E] = sensor input for control circuit 2 P base setup / operation with second control circuit.</li> </ul>

# 9.5.2 Setting for operation modes 5.01...5.02

5.01 Volume control, Setpoint in m<sup>3</sup>/h

5.02 Volume control for ventilation systems setpoint depending on outdoor temperature

Settings for controller output with function 2A (by analogue signal @ IO Setup, by MODBUS @ members menu).

Main menu	Setting
Start	
Setting	
Protocol	
Rase setun	
Controller Setup	
	-
Setting	Setpoint1
	Setting Setpoint in m <sup>3</sup> /h
530 m <sup>3</sup> h	Setting range: depending on measuring range of sensor and "K factor"
Setpoint1	Factory setting: 530 m <sup>3</sup> /h
Setting	Setpoint2
	Setting "Setpoint 2" e.g. reduced value for night operation.
	Switch over Setpoint 1/2 by external contact (display as long as no allocation is carried
Setpoint2	out: @ IO Setup).
	-
Setting	Pband
	Narrow control range = Short control times
530 m <sup>3</sup> h	Wide control range = Longer control times and more stable control
Pband	Setting range: depending on measuring range of sensor and "K factor"
	Factory setting: 530 m <sup>3</sup> /h
Setting	Min. Speed
	Setting range: 0 "Max. Speed"
0 %	Factory setting: 0 %
Min. Speed	
•	



Setting	Maximal Speed	
	Setting range: 100 % "Min. Speed"	
100 %	Factory setting: 100 %	
Max. Speed		
Setting	Manual mode	
	"OFF" = automatic control as function of the set parameters (Factory setting)	
OFF	"ON" = automatic control without function, speed setting in menu "Speed manual"	
Manual mode		
Setting	Speed manual	
	Manual speed setting without influence by the external signal.	
100 %	Activation by menu "Manual mode" or external contact at digital input ( PIO Setup).	
Speed manual	Setting range: 0100 % ≙ "Min. Speed" "Max. Speed"	
•	Factory setting: 100 %	
	For information about deactivated regulation the adjusted value for manual speed is indicated alternating with the actual value.	

#### Additional menu item for mode 5.02 with outside-temperature dependent target-setpoint



An outside temperature compensation can be activated (sensor connection "E2" to "Analog In 2") when being operated as a air volume regulation device.

An optimal building climate, e.g., can be achieved through this. Through this function, the set and active Setpoint 1/2 is automatically changed proportional to the measured outside temperature (@ Info: "Setpoint control").

S1 Setpoint1 S2 Setpoint2 P-Min SA Minimum air volume T-min Minimum temperature T-Start Setpoint reducing will start below this outside temperature AT Outdoor temperature

Setting	T-Band SA
	Temperature range in which the setpoint change continiously with outside temperature
30.0 K	Setting range: 0.0100.0 K
T-Band SA	Factory setting: 30.0 K
Setting	T-Start SA
	Setpoint reducing will start below this outside temperature
15.0 °C	Setting range: -10.040.0 °C
T-Start SA	Factory setting: 15.0 °C
Setting	Min. Setpoint
	Minimum pressure for very low outside temperature
700 m <sup>3</sup> h	Setting range: depending on measuring range of sensor and "K factor"
Min. Setpoint	Factory setting: 700 m <sup>3</sup> /h
1	





# 9.6 Air velocity control 6.01

# 9.6.1 Base setup 6.01

Main menu	Base setup
Start	—
Setting	
Protocol	
Base setup	
Controller Setup	
Base setup	Mode
	Mode selection 6.01
6.01 Mode	
Base setup	E1 Analog In
	The sensor input is factory set for mode <b>6.01</b> to sensor type "MAL1 ".
MAL1	Measuring range: 01 m/s
E1 Analog In	Output signal: 0 - 10 V
	Connection terminals: "E1", "GND", "24V"
	Other settable sensors / measuring ranges:
	<ul> <li>MAL10 (010 m/s, output signal 0 - 10 V)</li> </ul>
	<ul> <li>MAL15 * (015 m/s, output signal 0 - 10 V)</li> </ul>
	<ul> <li>MAL20 * (020 m/s, output signal 0 - 10 V)</li> </ul>
	<ul> <li>0 - 10 V, 0 - 20 mA, 4 - 20 mA (for sensors with free measuring range and linear characteristic)</li> </ul>
	The sensor measuring range must be entered for sensors with free measuring range in order to display the actual value correctly.
	Example 0 - 10 V sensor and measuring range 0 - 5 M/s:
	E1 Analog in = $0 - 10^{\circ}$ V, E1 Unit = m/s, E1 Decimals = 1, E1 Min. = 0,0 m/s, E1 Max. = 5 m/s
	* Alternative measuring ranges which can be selected by jumpers for sensor type MAL10.
Base setup	E1 Offset
	Sensor calibration with calibrated comparison device.
0.00 m/s E1 Offset	The current "E1 Actual" is displayed including the offset set here.
Base setup	Adjustable "E2 Function"
OFF	• [1E] = external setpoint e.g. by external signal (0 - 10 V) instead of setting "Setpoint 1" 0 - 10 V 0 0 - 100 % conser measuring range
E2 Function	1.0 - 10V = 0 - 100% sensor measuring range.
	between settings on the device and external manual operation via digital input ( IO Setup: function [7D]).
	<u>3E</u> = Sensor average to E1
	• 4E = Sensor comparison to E1
	• 5E = Sensor difference to E1
	• [6E] = sensor for outdoor temperature-dependent setpoint adaptation, pre-
	programmed sensor type TF
	- menu group Setury additional parameter: I-Band, I-Start SA, Min. Setpoint.
	- wienu group IIIIO additional parameter: Setpoint control
	<ul> <li>Example Setting for operation (2001 (2005) / additional menu items.</li> <li>[75] = Measurement value = Measurement value a star limit indication disclose in</li> </ul>
	Info menu "E2 Actual".
	<ul> <li>[8E] [13E] = sensor input for control circuit 2 @ base setup / operation with second control circuit.</li> </ul>



## 9.6.2 Settings for operation modes 6.01

6.01 Air velocity control, Setpoint in m/s

Settings for controller output with function 2A (by analogue signal @ IO Setup, by MODBUS @ members menu).

Main menu	Setting
Start	
Setting	
Protocol	
Base setup	
Controller Setup	
Base setup	Setpoint1
	Setting range: in measuring range of sensor
0.50 m/s	Factory setting: 0.50 m/s
Setpoint1	
	_
Base setup	Setpoint2
'	Setting "Setpoint 2" e.g. reduced value for night operation.
	Switch over Setpoint 1/2 by external contact (display as long as no allocation is carried
	out: @ IO Setup).
Setpoint2	
	_
Basa satun	Phand
	Varrow control range = Short control times
0.50 m/s	Wide control range - Longer control times and more stable control
0.50 m/s	Sotting range, in measuring range of consor
Pband	
Base setup	Min. Speed
	Setting range: 0 "Max. Speed"
0 %	Factory setting: 0 %
Min. Speed	
Base setup	Max. Speed
	Setting range: 100 % "Min. Speed"
100 %	Factory setting: 100 %
Max. Speed	
Base setup	Manual mode
	"OFF" = automatic control as function of the set parameters (Factory setting)
OFF	"ON" = automatic control without function, speed setting in menu "Speed manual"
Manual mode	
Base setup	Speed manual
	Manual speed setting without influence by the external signal.
100 %	Activation by menu "Manual mode" or external contact at digital input (@ IO Setup).
Speed manual	Setting range: 0100 % ≙ "Min. Speed" "Max. Speed"
	Factory setting: 100 %
	For information about deactivated regulation the adjusted value for manual speed is
	indicated alternating with the actual value.





# 9.7 Menu group Start

Main menu	Start
Start	
Settings	
Protocol	
Base setup	
Controller Setup	
Start	PIN input
	The service menu for the installation can be protected against unintentional changes
PIN input	by a pin code. With further pin codes putting back to pre-setting is possible.
	PIN 0010
	Opening service menu, if PIN-protection activated.
	DIN 1224
	Change "acting"
	Upering Setting .
	ii set protection – ON ( $(g^{-}$ Controller Setup)
	PIN 9090
	Restore user setting.
	PIN 9091
	Save user setting (corresponds function "Save user setup" = "ON" Controller Setup)
	PIN 9095
	Restore factory setting = delivery status
	Exception:
	The stored events in the "Protocol" menu are retained after resetting to factory setting!
Start	Language
GB	Menu language by the factory set to English.
Language	In this menu different national languages can be selected (GB = English, D = German
	·).
	US Einheiten
OFF	The display can be switched between SI units and imperial (US) units =>US units ON.
US Einheiten	SI units (factory setting): °C, bar, Pa, m³/h, K-Factor, m/s
	Imperial (US) units: °F , psi, in.wg, cfm, K-Faktor US, ft/s
	Settings for temperature differences (with SI units in K) are also made for Imperial units
	(US) in °F ( $\Delta$ 1.8 °F $\triangleq \Delta$ 1 K).
	Conversion factors:
	<ul> <li>Temperature: t / °F = 1,8 x t °C + 32.</li> </ul>
	• Pressure: 1,0 psi = 0,069 bar, 1,0 in.wg = 254 Pa
	• Air flow: 1,0 cfm = 0.5885 m <sup>3</sup> /h, inlet ring: K-Factor US = 9,3 x K-Factor SI
	<ul> <li>Speed: 1.0 ft/s = 0.3048 m/s</li> </ul>
	In order to refresh the display, the desired mode must be confirmed again after switch- ing over the units ( Base setup)!
Start	Reset
OFF	Complete re-start of the device
Reset	
Start	Mode
1.01	Query of the operating mode (e.g. <b>1.01</b> for speed controller)
Mode	





Start	Device name
9.15	Display of device name and software version
ххх	
Start	Individual unit number
SN: 154036311039	
	1

# 9.8 Menu group Info

The first menu item in the Info menu group is displayed (display dependent on selected mode) after switching on the line voltage or after exiting the setting menu with the Esc key combination. Settings cannot be made in this menu group!

	Info for mode sp	beed controller 1.01
Info	Lovel modulation control out	out
0%	The percentage modulation f	actor is displayed in addition to the bar chart
0 %	The percentage modulation i	
Control		
Info	Display of the currently active	e default signal.
0 %	The percentage corresponds	to the internal actuation of the device under consideration
Set external1	of the settings with speed a $0 - 100\% + 0 - 10\% + 10 - 0\%$	Ind Max. speed .
	0 - 100 % = 0 - 10 %, 10 - 0 %	The device operates at:
	"Set external1"	Signal to "F1" / "GND"
	"Set external?"	Signal to "E?" / "GND"
	"Set Intern1"	Menu "Set Intern1"
	"Set Intern?"	Menu "Set Intern?"
	Info for mode co	ontroller 2.01 6.01
Info	Only for mode 2.05	
0°C	Current actual value different	ce sensor 1 - sensor 2 (unit depending on the program-
E1-E2 actual		
Info	Only for mode <b>2.04</b> , <b>3.03</b> , <b>3</b>	<b>.04</b> (E2 function = [4E])
0 °C	The highest value determine	d automatically from two sensor measuring values which
Control value	is used as the actual value for	or the control (unit depending on programming).
Info	Only for mode <b>2.04</b> program	med for averaging (E2 function = $3E$ ).
49.9 °C		
Average E1/E2		
Info	Current actual value measure	ed at sensor 1 (unit depending on programming).
0 °C		
E1 Actual		
Info	Display for "actual value 2" fo	or operation with two sensors.
0°C	Display if function not active:	
E2 Actual		



Info	Display of the active target value at which the device operates.	
0 °C	<sup>1</sup> "Setpoint1" Menu "Setting"	
Setpoint1	"Setpoint2" Menu "Setting"	
	<sup>-</sup> "Ext. Setpoint" = setting by external signal 0-10 V. With activated manual mode the display constantly changes between actual value and value for manual mode.	
	Display for operation with two control circuits:	
	"1.Setpoint 1" or "1.Setpoint 2" for control circuit 1	
	"2.Setpoint 1" or "2.Setpoint 2" for control circuit 2	
Info	Only for mode 4.02, 4.03, 5.02 with setpoint depending on outdoor temperature (E2	
100.0 Pa	function = $[6E]$ ).	
Setpoint control		
Info	Level modulation control output.	
0 %	In addition to the bar chart, the level of the output voltage is indicated.	
Modulation		
	The modulation for each control circuit is displayed in operation with two control circuits:	
	"1. Modulation" for control circuit 1	
	"2. Modulation" for control circuit 2	
Info	Momentarily status for minimum speed cut off	
OFF	" $ON$ " = switch off, if Setpoint (+/- "Min. speed cut off") is reached.	
Min. speed cut off	"OFF" = no switch off that means operation with minimum rate of air.	
	Display for operation with two control circuits:	
	"1. Min. speed cut off" for control circuit 1	
	"2. Min. speed cut off" for control circuit 2	

## 9.9 Controller Setup

### 9.9.1 PIN protection activate, PIN 0010

Controller Setup	The adjustments for the installation in the service level can be protected against
	unintentional modifications. To do this, activate the "PIN protection" = "ON".
OFF PIN Protection	In order to simplify the initial start-up operation, the service level in the factory setting is free = "OFF" i.e. accessible without <b>PIN 0010</b> .

### Available menu groups with activated PIN-protection

Main menu
Start
Setting
Protocol

If PIN-protection is switched on, it automatically becomes active after about 15 minutes without keys being pressed.

#### Possibilities for early activation of PIN protection:

- Execute the "Reset" function in the "Start" menu group.
- By switching the mains voltage off and then on again.



### Information

After installation of the device has been carried out, "PIN-Protection" should be activated = "ON"



### 9.9.2 PIN protection activate, PIN 1234

Controller Setup	The "Settings" menu for the user's basic settings (Setpoint, default value, min, max)
	are freely accessible when using the factory settings (i.e. without "PIN").
OFF Set protection	If necessary, these can also be protected against unauthorized modifications by using a " <b>PIN 1234</b> ". For this, the settings protection must be programmed to "ON". The settings menu is then no longer visible without inputting a PIN!
	Function only in combination with activated PIN-Protection!

#### Available menu groups with activated PIN-protection + setting protection

Menu	
Start	
Protocol	

#### 9.9.3 Save user settings restore with PIN 9090

Controller Setup	The individually made device configurations (User Setting) can be saved here (corre- sponds to PIN 9091).
OFF Save User Setup	By entering <b>PIN 9090</b> the individually made device configurations can be reestablished ( Start - PIN Input).
	A file (userconf.csv) is generated and saved on the main drive (root directory) when saving the user setting. The data can be accessed via the <b>ZAset</b> program.



#### Information

By entering the "PIN 9095" in the "PIN" menu of the "Start" menu group the device is reset to the asdelivered state (except for the saved events in the "Protocol"menu). Any changes that have been made to the settings are thus lost.

### 9.9.4 Sensor Alarm ON / OFF

The inputs "E1 Analogue In" and if Sensor 2 is activated "E2 Analogue In" are monitored. In case of an interruption or short-circuit in the sensor conductor, or in case of measured values that lie outside of the device's measurement range, a time-delayed fault indication takes place. Function only in controller mode (from **2.01**)!

Controller Setup	With "Alarm Sensors" = "ON" (factory setting). Indicated sensor disturbances are displayed as "Alarm" alternating to the actual value and stored in the menu of "Protocol".	
Alarm sensors	A programmed alarm relay (factory setting relay K2) indicates the sensor failure.	Sensor 1
Controller Setup	With "AlarmSensors" = "OFF" areindicated sensor disturban-	
OFF Alarm sensors	ces as "Message" alternating to the actual value and stored in the menu of "Protocol".	Sensor 1



### 9.9.5 Limit

Construction Costs un	After allocation of a divital input (777-10 Cature) on adjustable limitation of the medulation
Controller Setup	After allocation of a digital input ( 2 IO Setup) an adjustable limitation of the modulation
	can be activated via a digital input ("D1", "D2",).
	Display as long as no allocation has been carried out in "IO Setup":
Limit	The limitation influences both outputs in operation with two control circuits.



### 9.9.6 Minimum speed cut off

Controller Setup	This function is primarily significant for installation of the device as a pure P Controller in refrigeration and air-conditioning technology.
OFF	For operation mode speed controller <b>1.01</b> without function!
Min. speed cut off	Display for operation with two control circuits: "1. Min. speed cut off" for control circuit 1 "2. Min. speed cut off" for control circuit 2

#### Msco = OFF (factory setting)

If no "Min. speed" is adjusted, the fan stops with reaching the desired value. If "Min. speed" is adjusted (e.g. 20%), then no dis-

connection of the fan takes place. I.e., always a minimum ventilation is ensured (fan does not go under setting "Min. speed").

#### Msco. e.g. -2.0 K

It takes place a disconnection from setting "Min. speed" to "0", if the given difference is reached related to the desired value.

At a plus value (+) before reaching the desired value At a minus value (-) after falling below the desired value.





### 9.9.7 Reverse action of the control function

Controller Setup	For the effect of the regulation there are two functions:
ON Vals Satan I	ON for "Val>Set=n+"      increasing Fanlevel for increasing actual value over Setpoint.
vai>Set=n+	• OFF for Val>Set=ri+ = increasing Fanievel for decreasing actual value below Setpoint.
	Display for operation with two control circuits:
	"1. Actual>Set=n" for control circuit 1
	"2. Actual>Set=n" for control circuit 2
	For special applications an external switch over of the control function is possible (



### 9.9.8 Controller configuration

The "controller configuration" is automatically carried out during selection of the application related mode of operation (Base setup). The factory presets in accordance with the mode of operation are based on many years of experience, which is suitable for many applications. Under special circumstances, these can be individually adapted ( Panu group "setting").

Controller Setup	The type of control determines the method with which the controlled value behaves in
Р	case of a difference between the target and current values. For this, the control technology has standard algorithms, which consist of a combination of three methods:
Type of control	Selection P, PID:
	• <b>P</b> control (Proportional component, proportion of the absolute deviation)
	I control (Integral component, proportion of the sum of all deviations)
	• <b>D</b> control (Differential component, proportion of the last difference)
	Display for operation with two control circuits:
	"1.Controller type" for control circuit 1
	"2.Controller type" for control circuit 2
With pure P controllers (	controller type <b>P</b> ), the following described settings do not have any function.
If needed, the most suita proportions.	ble combination for the respective control system can be determined from these

The control configuration (KP, KI, KD, TI) is identical for both control circuits in operation with two control circuits. Fine adjustment is possible for each control circuit by the separate "Pband" setting.



Controller Setup	P-component = reaction time
50 % KP	Setting range: 0 - 200 % smaller = more slowly bigger = faster
Controller Setup	I-component = accuracy, correction time
50 % Kl	Setting range: 0 - 200 % bigger = faster smaller = more slowly
Controller Setup	D-component
50 % KD	<ul> <li>More "D-component" causes more stability by a clean actual value signal with shorter correction times</li> <li>By a actual value signal with a superposition should be done to attitude without "D-component" → 0 %</li> <li>Setting range: 0 - 200 %</li> <li>value smaller = less "D-component"</li> <li>value higher = more "D-component"</li> </ul>
Controller Setup	Integration time = correction time Setting range: 0 - 200 %
0 % TI	smaller = faster bigger = more slowly



#### 9.9.9 Group control

Fan groups can be activated by the analogue outputs "A1" and "A2", the relay outputs "K1" and "K2" or by the RS-485 interface for MODBUS RTU.

Controller Setup	Setting range 0 / 1
	Following group versions are available:
0	• <b>0</b> : One controlled group and up to three switched groups (factory setting)
Group version	1: Two controlled groups

#### Group control via analogue outputs and relays

- The groups must be connected at the appropriate programmed output when activating by the analogue outputs and relays.
- The assignment of the analogue outputs and the relays for the group control takes place in the IO Setup.
- The number of possible groups depends on the available hardware outputs in the MODBUS Master (maximum of 4 groups possible).

### Group control im MODBUS Master Operation

- If controlling via MODBUS, an individual function can be programmed for each group device.
- The virtual outputs are assigned after the menu group "MODBUS Master" for the respective component "fan 1"..."fan xx".
- The number of possible groups does **not depend** on the available hardware outputs in the MODBUS Master (maximum of 4 groups possible).

Group functions (@ IO Setup)

Analog output A1, A2 MODBUS A1, A2

Relay output K1, K2

8K = Group 2 12K = Group 3 13K = Group 4

2A = Group 1

5A = Group 2 11A = Group 3 12A = Group 4



### Information

- Group activation by analogue output, relay and MODBUS can also be combined.
- Ensure an ascending and complete sequence when assigning the groups. This means that if, for example, the function for a fourth group was assigned for an output, there must already be an assignment for groups 2 and 3 ( I lo Setup).
- The group control only becomes active once a group function is allocated to an output (analogue, relay, MODBUS).





#### 9.9.9.1 Variant "0": One controlled group and up to three switched groups

The programming described below applies equally for group control by analogue outputs, relay outputs and MODBUS.

For group control by the analogue outputs "A1" / "A2" and the relay outputs "K1" and "K2", the available outputs must be observed in the selection of the version (combinations are possible).

#### Example: Required assignment for a controlled and a switched group

- For activation by analogue output (@ IO Setup) or MODBUS (@ MODBUS Master)
  - Function A for group 1 (0 100 % controlled)
  - Function 5A for group 2 (0 / 100 % switched)
- For activation of Group 2 by relay (P IO Setup)
  - Function A for group 1 (0 100 % controlled)
  - Function 8K for group 2 (ON / OFF switched)

The function 11A must be allocated additionally to Group 3 for one controlled and two switched groups.

The function 12A must be allocated additionally to Group 4 for one controlled and three switched groups.

Controller Setup	Group 2 ON value
	Switch-on value for Group2
50 %	Setting range: 0 - 100 %
Group 2 ON value	Factory setting: 50 % *
Controller Setup	OFF Value Group2
	Switch-off value for group2
45 %	Setting range: 0 - 100 %
OFF Value Group2	Factory setting: 45 % *
Controller Setup	nmin at Group2
•	 Minimum Value for Group2
20 %	Setting range: 0 - 100 %
nmin at Group2	Factory setting: 20 % *
	_
Controller Setup	Group 3 ON value
	Switch-on value for Group3
70 %	Setting range: 0 - 100 %
Group 3 ON value	Factory setting: 70 % *
Controller Setup	OFF Value Group3
	Switch-off value for group3
65 %	Setting range: 0 - 100 %
OFF Value Group3	Factory setting: 65 *
	-
Controller Setup	nmin at Group3
	Minimum Value for Group3
30 %	Setting range: 0 - 100 %
nmin at Group3	Factory setting: 30 % *
Controller Setup	Group 4 ON value
	Switch-on value for Group4
85 %	Setting range: 0 - 100 %
Group 4 ON value	Factory setting: 85 % *



Controller Setup	OFF Value Group4
80 % OFF Value Group4	Switch-off value for group4 Setting range: 0 - 100 % Factory setting: 80 % *
Controller Setup	nmin at Group4
40 % nmin at Group4	Minimum Value for Group4 Setting range: 0 - 100 % Factory setting: 40 % *

\* Display as long as no group assignment via analogue output, relay, MODBUS: ----

Higher settings must be selected for following groups and the switch-off value of the group must be below the switch-on value.

### Example version "0" via MODBUS



### Function

Group 1 is continuously controlled (0 - 100 %), the other groups are switched on and off depending on the degree of modulation (0 / 100%).

If the modulation level exceeds the switch-on point "ON Value Group2", the MODBUS Master switches on the second group and the speed of the first group is reduced to an adjustable minimal value "nmin at Group2".

Then the speed of the first group increases to maximum within the remaining range.

If a third group is programmed up to switch-on point "ON Value Group3" etc.

Switch-off point "OFF Value Group2" at diminishing speed requirement.



Controller Setup	Group 2 ON value
	Switch-on value for Group2
50 %	Setting range: 0 - 100 %
Group 2 ON value	Factory setting: 50 % *
Controller Setup	OFF Value Group2
	Switch-off value for group2
45 %	Setting range: 0 - 100 %
OFF Value Group2	Factory setting: 45 % *
Controller Setup	nmin at Group2
	Minimum Value for Group2
20 %	Setting range: 0 - 100 %
nmin at Group2	Factory setting: 20 % *

\* Display as long as no group assignment via analogue output, relay, MODBUS: ----



#### Example version "1": Two controlled groups

#### 9.9.10 Display text for external message

Controller Setup	Alternatively to the "External Error" display when an external message occurs ( PIO
External error External message	<ul> <li>Alternatively to the External Error display when an external message occurs (C=10)</li> <li>Setup / Digital Inputs "D1" / "D2" the following error texts can be programmed:</li> <li>EC Motors</li> <li>Filter</li> <li>Frost protection</li> <li>Adiabatik</li> <li>Firealarm</li> <li>Pressure switch</li> <li>Ges alarm</li> </ul>
	<ul> <li>Water alarm</li> <li>RCD</li> </ul>



RCD Residual-current-operated protective device

# 9.9.11 Offset control signal

Controller Setup	Offset control sig. 1
0 % Offset control sig. 1	If required, the characteristic of the control signal for control circuit 1 can be adjusted.
	To activate this function, re-program the output with function 2A to function 14A.
	Setting range: 0 - 50 %
	Factory setting: 0 % (characteristic curve unchanged)



# 9.9.12 Selection amplifier (comparator) control circuit 1 or 2 at output A1

Controller Setup	If using two control circuits, the control circuit with the higher modulation can be
OFF Selection amplifier	This function can be used for refrigeration systems with combined refrigerant circuit and floating brine pressure control circuits, for example.
	Example:
	• Control circuit 1 is used for the refrigerant circuit. A pressure sensor is connected to determine the actual value. The setpoint and control range are set in bar.
	<ul> <li>Control circuit 2 is used for the brine pressurised circuit. A temperature sensor is connected to determine the actual value. The setpoint and control range are set in C° / K.</li> </ul>
	• Depending on which control circuit produces the higher modulation (depending on the measured and set values), the pressure control or temperature control is used as a specification for the power component.
	Selection amplifier = OFF (factory setting)
	No comparison of the two control circuits.
	Selection amplifier = ON
	Comparison of the modulation of control circuit 1 and control circuit 2 with automatic control active at the highest value.





## 9.9.13 Data on the total control deviation

The total control deviation is comprised of the sum of the control deviations for performance quantities and work quantities combined and refers to the specified areas.

In direct reference to the acquired input and controlled variables, the maximum deviation to the target value is  $< \pm 5$  %. By activating the menu-assisted adjustment, the total control deviation can be reduced to a value of  $< \pm 1$  %.

For indirect reference of the acquired input value to the controlled variable, i.e., two physical variables still need to be converted, the deviation can be reduced to  $< \pm 5$  % through adjustment.

In the case of an internal default value through the integrated or external terminal, the control deviation remains at  $< \pm 0.5\%$ .

## 9.10 IO Setup

#### 9.10.1 Analog outputs "A1"/ "A2"

IO Setup	The analog outputs 0 - 10 V (A1 and A2) can be allocated with various functions.
1. Control signal (2A) A1 Function	
IO Setup	With the settings "A1 min." / "A2 min." and "A1 max." / "A2 max." the characteristic of the output voltage can be adapted.
0.0 V A1 min.	Setting range: — "A1 min." / "A2 min." = 0 - 10 V
IO Setup	"A1 max." / "A2 max." = 0 - 10 V
10.0 V A1 max.	Factory setting: "A1 min." / "A2 min." = 0 V "A1 max." / "A2 max." = 10 V
	The setting for "A1 min." / "A2 min." must be below "A1 max." / "A2 max.".





IO Setup	Inverting of the output voltage is possible with the settings "A1 Inverting" / "A2 Inverting".
OFF A1 Inverting	Factory setting: Inverting = "OFF"

Function	Description
OFF	no function
Constant voltage 10 V	Constant voltage +10 V
(1A)	Factory setting for "A2" at operation with one control circuit.
1st control signal	Controlled 0 - 10 V output for control circuit 1 (factory setting for "A1")
(2A)	
E1	proportional input "E1"
(3A)	
E2	proportional input "E2"
(4A)	
Group2	Group control ( Controller Setup - group 2)
(5A)	
2.Cooling	Only for mode <b>2.03</b> temperature controller with additional functions.
(6A)	Controller output 2 with rising activation at Actual>Nominal = <b>Cool</b> .
2.Heating	Only for mode <b>2.03</b> temperature controller with additional functions.
(7A)	Controller output 2 with rising activation at Actual <nominal <b="" =="">Heat.</nominal>
2. control signal	Controlled 0 - 10 V output for control circuit 2 (factory setting for "A2" at operation with second control circuit)
(6A)	Control circuit 2 can be activated by programming the E2 function if required ( Base setup / operation with second control circuit).
Speed (9A)	proportionally 1.Control signal
Group3 (11A)	Group control ( Controller Setup - group 3)
Group4 (12A)	Group control ( Controller Setup - group 4)
Offset control sig. 1	Offset control signal 1
(14A)	Setting offset @ Controller Setup





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## 9.10.2 Digital inputs "D1" / "D2"

#### 9.10.2.1 Menu overview

IO Setup	
OFF D1 Function	Possible functions for D1 @ following table.
IO Setup	
OFF D1 Inverting	To invert the function, switch to "ON" (display [] as long as no function is allocated for D1).
IO Setup	With networking the digital inputs can be replaced by control over bus (Slave interface
ON D1 Busmode	2A/2B). With mode of operation <b>4.03</b> pre-setting of "D1" is ON. If bus mode is at ON, the digital input can be set by coil register c0 for D1.
IO Setup	
OFF D2 Function	Possible functions for D2 @ following table.
IO Setup	
OFF D2 Inverting	To invert the function, switch to "ON" (display as long as no function is allocated for D2).
IO Setup	With networking the digital inputs can be replaced by control over bus (Slave interface
ON D2 Busmode	2A/2B). With mode of operation <b>4.03</b> pre-setting of "D2" is ON. If bus mode is at ON, the digital input can be set by coil register c1 for D2.
IO Setup	If the digital inputs have the <b>same</b> function allocation (also applies for timer function)
OG D - D Relation	you can choose between an AND and OR operation. OR operation (factory setting). The function becomes active <b>when one</b> of the digital inputs or the timer is activated.
	<b>AND</b> operation. The function becomes active <b>when all</b> digital inputs or also the timer are activated.

Function	Description
OFF	No function (factory setting)
Enable (1D)	Enable (remote control) "ON" / "OFF"
External error (2D)	External fault alarm
Limit (3D)	"Limit" ON / OFF Influences control circuit 1 and control circuit 2 in operation with two control circuits
E1 / E2 (4D)	Switch over input "E1" / "E2" (for operation with one control circuit)
Reset (10D)	Complete re-start of the device





Max. Speed (11D)	Setting Max. Speed "ON" / "OFF"	
	Influences the respectively set value "1. Max. Speed" and "2. Max. Speed" in operation with two control circuits.	
Override Time	Overwrite timer function (in operation with timer)	
(21D)	The timer output is overwritten for a settable time with a selectable status (ON / OFF).	
	For Mode Speed controller 1.01	
Setpoint1/2	Switch over "Set Intern1" / "Set Intern2"	
(5D)	"Setting External 1" must be at "OFF".	
Setpoint int./ext. (6D)	Switch over "Intern" / "Extern"	
For modes as controller (from 2401.)		
Setpoint1/2	Switch over "Setpoint 1" / "Setpoint 2"for control circuit1	
(5D)		
Setpoint int./ext.	Switch over "Intern" / "Extern"	
(6D)	Possible only for operation with one control circuit!	
Control/Manual	Switch over "automatic control" / "Speed manual"	
(7D)	Possible only for operation with one control circuit!	
Heating/Cooling (8D)	Switch over control function (e.g. "heating" / "cooling")	
4 Cotra I Dhom d4/2	for control circuit 1: Switch over Setpoint 1/2 and Pband 1/1	
(15D)	When programming this function, "Setting" additionally lists the parameter: "1.Pband2 for control circuit 1."	
	Only active in operation with a second control circuit!	
E1 / E2 (4D)	The output for control circuit 2 is set additionally to "A2" to "A1" (regardless of the programmed function for "A1"). Control circuit 1 has no output for the duration of the switching.	
(40)	The switch over input "E1" / "E2" as in operation with one control circuit is no longer possible.	
2. Setpoint 1/2 (9D)	for control circuit 2: Switch over "2. Setpoint 1" / "2. Setpoint 2"	
2 Sotn±Dhand1/2	for control circuit 2: Switch over Setpoint 1/2 and Pband 1/2	
2.Setp+Pband1/2 (16D)	When programming this function, "Setting" additionally lists the parameter: "2Pband2 for control circuit 2."	

# 9.10.2.2 Enable ON/OFF function 1D

Remote ON/OFF by potential-free contact.

Activation of the members (speed setting) by analogue output and MODBUS interface is switched off, the other signal inputs and outputs stay active.

The device can still be operated in the switched-off state after pressing the "Esc" key combination.

- A programmed operating indicator relay (factory set "K1 function" = [1K]) reports the switch-off.
- A programmed alarm relay (factory set "K2 function" = [2 K]) does not report the switch-off.





Attention! No disconnection (isolation) when turned off, in accordance with VBG4 §6)!



# 9.10.2.3 External message, Function 2D

Connecting an external alarm indication (via floating contact). The device continues to work unchanged during an external indication to the digital input; the alarm symbol appears in the display. This indication can be issued via the relay contacts (K1 K2) (P IO Setup function K1, K2).

Info 🇳	<ul> <li>Indication during closed contact (factory setting): "D1 Inverting" = "OFF"</li> <li>Indication during opened contact: "D1 Inverting" = "ON"</li> </ul>
	Alternative display texts for error message @ Controller Setup / display text for external message.
External error	
Display alternating with ac- tual value display	

## 9.10.2.4 Limit ON / OFF, Function 3D

The value for "Limit" adjusted in the Controller Setup, is activated over a digital input. Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").

For "D1 Inverting" = "OFF", limitation active at closed contact.

The limitation influences both outputs in operation with two control circuits.



1 Setting "Limit" (depending on device type in: %, Hz, rpm)



# 9.10.2.5 Switch over input "E1" / "E2", function 4D

# (operation with one control cicuit)

Switch over between Input signal 1 (Analog In 1 terminal "E1") and input signal 2 (Analog In 2 terminal "E2").

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").



### Si 1 Signal 1

Si 2 Signal 2

For mode speed controller (**1.01**) Base setup for "E2 Analog In": **1**E necessary. For modes controller (from **2.01**..) Base setup for "E2 Analog In": **7**E necessary (as far as otherwise does not occupy).

## 9.10.2.6 Output control circuit 2 additional to "A2" on "A1", function 4D

The output for control circuit 2 is set additionally to "A2" to "A1" (regardless of the programmed function for  $\boxed{A1}$ ). Control circuit 1 has no output for the duration of the switching.

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").

At "D1" Inverting "OFF" the output of control circuit 2 also influences output "A1" when the contact is closed.



# 9.10.2.7 Set 1/2 or Setpoint 1/2, Function 5D

For Mode Speed controller **1.01**: Switch over "Set Intern1" / "Set Intern2 " Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").



1 Setting "Set Intern1" (depending on device type in: %, Hz, rpm) 2 Setting "Set Intern2" (depending on device type in: %, Hz, rpm)

- "D1 Inverting" = "OFF": "Set Intern1" at opened contact / "Set Intern2" at closed contact.
- "D1 Inverting" = "ON": "Set Intern1" at closed contact / "Set Intern2" at opened contact.





### For operation as controller (starting from 2.01): switch over "Setpoint 1" / "Setpoint 2" For operation with second control circuit: switch over "1.Setpoint 1" / "1.Setpoint 2"

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" -"24 V").



- "D1 Inverting" = "OFF": "Setpoint1" = 18 °C • at opened contact / "Setpoint2" = 25 °C at closed contact.
- "D1 Inverting" = "ON": "Setpoint1" = 18 °C at closed contact / "Setpoint2" = 25 °C at opened contact.

Setting "Setpoint 1" or "1.Setpoint 1" (display in operation with two 1 control circuits for Setpoint 1 of control circuit 1) Setting "Setpoint 2" or "1.Setpoint 2" (display in operation with two control circuits for Setpoint 2 of control circuit 1) 2



#### 9.10.2.8 Intern / Extern Function 6D

# For Mode Speed controller 1.01: Switch over "Set Intern" / "Set external "

"Set extern1" under settings must be programmed to "OFF".

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" -"24 V").



- "D1 Inverting" = "OFF": "Set Intern1" at opened contact / "Setting Extern" at closed contact.
- "D1 Inverting" = "ON": "Set Intern1" at closed contact / "Set Extern" at opened contact.

Si 1 Signal

Setting "Set Intern1" (depending on device type in: %, Hz, rpm)

For operation as controller (starting from 2.01): switch over "Setpoint 1" / "external Setpoint" Possible only for operation with one control circuit!

Under Base setup "E2 function" programmed to function [1E] for "external setpoint". Contact at digital input e.g. "Digital In 1" = "D1" - "D1"





- "D1 Inverting" = "ON": Setting at the unit at opened contact / Signal Extern at closed contact
- "D1 Inverting" = "OFF": Setting at the unit at closed contact / Signal Extern at opened contact

1 External Setpoint e.g. 5 V ≙ 23.8°C ES Se Sensor

#### 9.10.2.9 Automatic control / speed manual Function [7D] (mode 2.01)

#### Possible only for operation with one control circuit!

Switch over between automatic control to set target value (depending on the activation: "Setpoint1", "Setpoint2") and the default for "manual operation" set at the device.

If for Analog In 2 "E2 function" is programmed to [2E] switch over between "Setpoint1" or "Setpoint2" and external manual operation. With activated manual mode the display constantly changes between "actual value" and value for "manual mode".

Contact at digital input e.g. "Digital In 1"



"D1 Inverting" = "OFF" Automatic control at opened contact / manual operation at closed contact.

"D1 Inverting" = "ON": Automatic control at closed contact / manual operation at opened contact.

2 3

Setting "Setpoint2" Setting "Speed manual" (depending on device typ<u>e in</u>: %, Hz, rpm) Signal for Manual mode extern, E2 Function = <u>2E</u> ĒΗ

Sensor Se

#### 9.10.2.10 Reverse action of control function (2.01), Function [8D]

Switchover between: Increasing modulation during increasing actual-value and increasing modulation during sinking actual-value.

The factory presets for the "Control function" are dependent on the selected mode of operation (@ Controller Setup - reverse operation of the control function).

When switching over via a digital input, the device works with the opposite function as set there. The inversion of the control function influences both circuits in operation with two control circuits.

Controller Setup	Settings in Controller Setup
	Display for operation with two control circuits:
ON	"1. Actual>Set=n" for control circuit 1
Val>Set=n+	"2. Actual>Set=n" for control circuit 2

#### 9.10.2.11 Switch over Setpoint 1/2 for control circuit 2 9D

Switch over between "2.Setpoint 1" and "2.Setpoint 2" (for operation with two control circuits)

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" -"24 V").



"D1 Inverting" = "OFF": "2. Setpoint 1" = 18 °C at opened contact / "2. Setpoint 2" = 25 °C at closed contact.

"D1 Inverting" = "ON": "2. Setpoint 1" = 18 °C at closed contact / "2. Setpoint 2" = 25 °C at opened contact.

1 Setting "2.Setpoint 1" = Setpoint 1 of control circuit 2 2 Setting "2.Setpoint 2" = Setpoint 2 control circuit 2



•

# 9.10.2.12 Setting Max. Speed ON / OFF function 11D

The value for "Max Speed" adjusted in menu "Settings", is activated over a digital input. I.e. the unit works independently of the controller function firm with this value.

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").

This function influences both circuits in operation with two control circuits.





Display depending on device type in: %, Hz, rpm 1 Setting "Max. Speed" or "1.Max. Speed" and "2.Max. Speed" for operation with two control circuits

#### 9.10.2.13 Switch over Setpoint 1/2 and Pband 1/2 for control circuit 1 [15D]

Switching between "1st setpoint 1" / "1st setpoint 2" and "1st Pband 1" / "1st Pband 2" (from 2.01, not for 2.03).

Function basically the same as [5D], it is additionally switched over to Pband 2.

When programming this function, "Setting" additionally lists the parameter: "1.Pband 2 for control circuit 2."

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" -"24 V").

Example for "D1 Inverting" = "OFF":

- With open contact: "1.Setpoint 1" = 20 °C + "1.Pband 1" = 5 K
- With closed contact: "1.Setpoint 2" = 17 °C + "1.Pband 2" = 3 K



#### 9.10.2.14 Switch over Setpoint 1/2 and Pband 1/2 for control circuit 2 [16D]

Switch over between "2.Setpoint 1" / "2.Setpoint 2" and "2.Pband 1" / "2.Pband 2" (only for operation with second control circuit possible).

Function basically the same as 5D and 9D, it is additionally switched over to Pband 2.

When programming this function, "Setting" additionally lists the parameter: "2Pband2 for control circuit 2."



Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").

Example for "D1 Inverting" = "OFF":

- With open contact: "2.Setpoint 1" = 20 °C + "2.Pband 1" = 5 K
- With closed contact: "2.Setpoint 2" = 17 °C + "2.Pband 2" = 3 K



### 9.10.2.15 Timer function overwrite 21D

The timer output can be overwritten for a settable time with a selectable status if required ( $\mathfrak{P}$  timer). To overwrite the timer function by pressing keys until the next timing change => "Override Time" = 0 min.

The override time is activated by pressing a key at a digital input (example for D1 not inverted). The bypass time can be ended prematurely by pressing another key.

If the contact remains closed, the override time also run out, then a short interruption is required to reactivate.



Contact depending on device type at terminals "D1" - "D1" or "D1" - "24 V"

Example: speed limitation over Timer (Function 3D)

The timer limits the maximum speed for a certain period of time (e.g. timer ON from 6:00 - 10:00 am). With the "Override Timer" contact the limitation (from 6:00 - 10:00 am) activated by the timer can be cancelled for an adjustable period "Override Time" ( timer function overwritten: Override Status = OFF)

To activate the limitation outside the programmed time (10:01 - 5:59 am) => "Override Status" = ON



# 9.10.3 Configuration of analog inputs "E1" and "E2"

# 9.10.3.1 Signal adaption E1 and E2

If required, an adaptation of the specification signal / speed characteristic curve is possible



**Information** Setting options depending on the version of the software available! These settings are mostly practical for the operating mode with rotational speed specification over an external signal. In operating modes (as of 2.01) this setting is not suited for influencing the regulation process.

r	T. C.
IO Setup	
0 E1 Modus	<ul> <li>E1 Modus</li> <li>[0] = E1 min. / E1 max. without function (factory setting)</li> <li>[1] = Offset / turn</li> <li>[2] = signal range</li> <li>[3] = Hysteresis setting On / Off (function depending on the version of the software available)</li> </ul>
IO Setup	
0 % E1 Min.	E1 Min. Setting range: 0 - 100 % Factory setting: 0 %
IO Setup	
0 % E1 max	E1 max Setting range: 0 - 100 % Factory setting: 100 %
IO Setup	
0 E2 Mode	E2 Mode 0 = E2 min. / E2 max. without function (factory setting) 1 = Offset / turn 2 = signal range
IO Setun	
0 % E2 min.	<b>E2 min.</b> Setting range: 0 - 100 % Factory setting: 0 %
IO Setup	
0 % E2 max.	<b>E2 max.</b> Setting range: 0 - 100 % Factory setting: 100 %




# Example for Mode "1.01" with speed setting signal 0 - 10 V

#### Modus 1

Example: "E1 min." = 20 % The controller begins only at approx. 20% higher signal with minimal modulation.

Example: "E1 max." = 80 % The modulation rises linear to 100% modulation with 80% setting signal.

#### Modus 2

Example: "E1 min." = 30 % Only with approx. 30 % setting signal the controller begins with approx. 30% modulation.

Example: "E1 max." = 80 % Over 80 % setting signal the modulation is switched to 100 % modulation.

#### Modus 3

Example: "E1 min." = 30 %, "E1 max." = 80 % Over approx. 80 % setting signal the modulation is switched on. Below approx. 30 % setting signal the modulation is switched off.

For a correct function: E1 min. higher 0 % and E1 max. below 100 %. example 2 and 3 only for information.

Idealized principle diagrams for setting: "Min. Speed" = 0 % and "Max. Speed" = 100 %

1 2 3 4 5 6 7 8 9 10 0-10V



0



Si E

12.10.2009 v\_e1\_modus\_3\_prz.vsd

## 9.10.3.2 Inverting analog inputs "E1" / "E2"

After programming the signal or sensor type, an inversion of the inputs can be carried out.

	-
IO Setup	Factory setting for Inverting inputs = "OFF" (if input activated) (signal: 0 - 10 V, 0 - 20 mA, 4 - 20 mA).
OFF E1 Inverting	For activation using inverted default signals or sensors with inverted output signals proportional to the measurement range, switch inverting to "ON" (Signal: 10 - 0 V, 200 mA, 20 - 4 mA).
IO Setup	-
OFF E2 Inverting	_

Example: mode **1.01** speed controller, setting by external signal



MODBUS Out: speed setting over MODBUS Analog Out: speed setting over analog output 0 - 10 V Si Signal OFF Inverting = OFF ON Inverting = ON

# 9.10.3.3 "E1" / "E2" Bus mode

After programming the signal or sensor type, the raw value (0-32767) of an analog sensor input can be written in a Holding Register (h9000 for E1 and h9001 for E2) with the bus mode activated. The connection is made at the MODBUS RTU Slave interface. Connecting terminals: 2A (2D+), 2B (2D-).

IO Setup	The bus mode of the inputs is set to "OFF" at the factory.
	With activated bus mode, the raw values can be written accordingly into the Holding
OFF	Registers, addresses h9000 and h9001 for "E1" and "E2".
E1 Busmode	
IO Setup	
OFF	
E2 Busmode	
EE Buomoue	_



# 9.10.4 Function and inverting for relay outputs "K1" and "K2"

IO Setup	Various functions can be allocated to the relay outputs "K1" and "K2". In case of the					
Operating indication (1K) K1 Function	same function allocation for "K1" and "K2", these work parallel. The inversion of the relays "K1" and "K2" is set at the factory to "OFF" (when a function is programmed). For switching inversion to "ON" (switching behaviour dependent on assigned function).					
IO Setup	working. Three-phase current devices must have at least 2 line phases!					
OFF	······································					
K1 Inverting	_					
IO Setup						
Fault indication						
(2K)						
K2 Function	_					
IO Setup						
OFF						
K2 Inverting						

Function	Description			
	No function			
OFF	Relays remain always de-energized.			
Operating indication	Operating indication (factory setting for "K1", non inverting).			
(1K)	Operation without fault, reports enable "OFF"			
Fault indication	Fault indication (factory setting for "K2", non inverting).			
(2K)	Pulled up in operation without fault, with release "OFF" not dropped out.			
	Drops out in case of line and device fault and external fault at the digital input. Depending on programming in event of sensor failure.			
	When networked via the MODBUS Master interface, fault indication in case of faulty MODBUS connection and fault on a member.			
External error	External fault separate with message at digital input (factory setting if terminals			
(3K)	bridged).			
Limit modulation	Limit modulation			
(4K)	Over or falling below limits for modulation.			
Limit E1	Limit "E1"			
(5K)	Whenover or falling below limits for input signal "E1".			
Limit E2	Limit "E2"			
(6K)	Whenover or falling below limits for input signal "E2".			
	For modes as controller (from 2.01.)			
Setpoint Offset	Limit: Setpoint offset (only for active Setpoint control circuit 1).			
(7K)	Deviation between actual value and setpoint to high.			
Group2	Group control (Group 2)			
(8K)	Switching on fans depending on modulation			
Group3	Group control (Group 3)			
(12K)	Switching on fans depending on modulation			
Group4	Group control (Group 4)			
(14K)	Switching on fans depending on modulation			
	For modes as temperature controller with additional functions 2.05			
2.Heating	Heating function			
(9K)	Switch ON point: temperature = Setpoint +/- Offset			
0.0	Switch OFF point: Temperature around hysteresis over switch ON point			
2.Cooling	Cooling Tunction			
(IUK)	Switch OEE point: temperature – Setpoint +/- Uffset			
	Switch OFF point. Temperature around hysteresis below switch ON point			



- K1 1 = energized, terminals 11-14 bridged 0 = de-energized, terminals 11-12 bridged
   K2 1 = energized, terminals 21-24 bridged 0 = de-energized, terminals 21-22 bridged

Function	Controller status		K1/ K2	
	1 = er		ergized	
		0 = de-e	nergized	
		Inve	rting	
		OFF	ON	
1K	Operation without fault, line supply okay	1	0	
2K	Fault with indication by relay	0	1	
3K	External Fault at digital input for external fault	1	0	
4K	Over or falling below modulation	1	0	
5K	over or falling below limits for input signal "E1"	1	0	
6K	over or falling below limits for input signal "E2"	1	0	
7K	setpoint deviation to high	1	0	

# 9.10.5 COM2 Function

IO Setup	Possible settings:			
MODBUS Slave COM2 Function	<ul> <li>MODBUS Slave (factory setting): In the main menu the "Diagnostic" menu group is followed by the "MODBUS Slave" menu group. The communication parameters can be set in this.</li> <li>OFF: The "MODBUS Slave" or "MODEM SMS" menu group is not displayed in the main menu.</li> <li>MODEM SMS: In the main menu the "IO Setup" menu group is followed by the "MODEM SMS" menu group. Input SIM PIN for MODEM SMS interface (no function at present).</li> </ul>			



# 9.11 Limits

# 9.11.1 Limit indication depending on modulation

only for Modulation control circuit 1!

Display for operation with two control circuits: 1.Modul. function, 1.Modulation min., 1.Modulation max., 1.Modul. Delay

Limits	Following functions can be allocated to the limit indication		
OFF Controller function	OFF none Function (factory setting)		
	Failure (1L)	Limit alarm alternating with actual value display Is listed in the protocol as an alarm. Indication with the centralized fault of a programmed relay (IO allocation Function $2K$ ).	
	Message (2L)	Is listed in the protocol as a message. There is no alternating message on the actual value display and no message via alarm relay.	
	Filter error (3L)	Like function 1L with fault message "Filter"	
	Filter Message (4L)	Like function 2L with fault message "Filter"	
	In the IO setup, a s	separate relay can be allocated independent of these settings.	
Limits	If the modulation exceeds the set "Level max" value, this is reported until the set value		
30 % Level min.	"Level min" has been undercut. The indication is delayed by the time set in "Display delay". Setting range: 0 - 100 % Factory setting: 30 % / 40 % *		
Limits	-		
40 % Level max.	-		
Limits	Time delay exceed	ding "Level max." up to indication by relay and alarm symbol.	
2 sec Level Delay	Setting range: 0 - Factory setting: 2 :	120 sec. sec. *	

\* Display ---- as long as function = OFF





### Example indication by relay "K1":



If "Level min." is higher than "Level max.", the "Level max." switching point is without hysteresi.

## 9.11.2 Limit indication depending on setting or sensor signal

Same procedure fo	r analogue inputs	"E1" and	"E2".
-------------------	-------------------	----------	-------

Limits	Following functions can be allocated to the limit indication			
OFF Lmt E1 Function	OFF	none Function (factory setting)		
	Failure (1L)	Limit alarm alternating with actual value display Is listed in the proto- col as an alarm. Indication with the centralized fault of a programmed relay (IO alloca- tion Function $2K$ ).		
	Message (2L)	Is listed in the protocol as a message. There is no alternating mes- sage on the actual value display and no message via alarm relay.		
	Filter error (3L)	Like function 1L with fault message "Filter"		
	Filter Message (4L)	Like function 2L with fault message "Filter"		
	In the IO setup, a	separate relay can be allocated independent of these settings.		
Limits  Lmt E1 min	Both values for E1 ("E1 min" and "E1 max") can be set independent of each other and act on a relay together if correspondingly programmed. If a function is activated or if a relay is allocated, both settings ("min" and "max") are initially at "OFF". Work can be carried out with one as well as with both limit indicators. The same setting applies to "E2 Min." and "E2 Max.", described below for "E1".			
Limite	Undercutting the signal ("E1 min").			
Limits	If the signal undercuts the set value "E1 min", this is reported until the set value (plus adjustable hysteresis) has been exceeded once again.			
	Exceeding the signal ("E1 max").			
Lmt E1 max.	If the signal exceeds the set value "E1 max", this is reported until the set value (minus			
	hysteresis) has be	een undercut once again.		
Limits	E1 Hysteresis			
	Hysteresis adjustment in the unit of measure of the programmed input signal.			
Lmt E1 Hyst.				



Limits	E1 Delay				
	ime delay exceeding "Level max." up to indication by relay and alarm symbol.				
	Setting range: 0 - 120 sec.				
Lmt E1Del.	Factory setting: 2 sec.				



### Information

Always adjust the value for the maximum input signal higher than the value for the minimum input signal!

E1 Max. > E1 Min.

# Example for a limit indication of default signal or sensor signal to "Analog In 1"



#### Settings: - E1 Max.: 80 %

- E1 Min.: OFF
- switching hysteresis 5 % (from
- 100 %)

#### Settings:

- E1 Min.: 20 %
- E1 Max.: OFF
- switching hysteresis 5 % (from 100 %)

#### Settings:

- E1 Min.: 20 %
- E1 Max.: 80 %
- switching hysteresis 5 % (from 100 %)

Terminal "E1" and "GND" alarm via relay "K1" (non-inverted) IO Setup  $\rightarrow$  K1 function: 5 K = limit indicators



# 9.11.3 Limit indication depending on (offset) to Setpoint

In operating modes as a controller (starting from **2.01**), two limit indicators can be carried out based on the set target value (Setpoint) and measured actual value (on E1).

Only for active Setpoint of control circuit 1!

Display for operation with two control circuits: 1.Offset function, 1.Offset 1, 1.Offset 2, 1.Offset hyst., 1.Offset Delay

Limits	Following functions can be allocated to the limit indication.		
	Identical setting for both analogue inputs "E1" and "E2".		
OFF Offset Function	OFF	none Function (factory setting)	
	<ul> <li>Limit alarm alternating with actual value display Is listed in the col as an alarm.</li> <li>(1L) Indication with the centralized fault of a programmed relay (IO tion Function [2K]).</li> </ul>		
	Message (2L)	Is listed in the protocol as a message. There is no alternating mes- sage on the actual value display and no message via alarm relay.	
	Filter error (3L)	Like function 1L with fault message "Filter"	
	Filter Message (4L)	Like function 2L with fault message "Filter"	
	In the IO setup, a	separate relay can be allocated independent of these settings.	
Limits	Offset 1, Offset 2	2	
Offset 1	Both values for Offset 1 and Offset 2 can be set independent of each other and act on a relay together if correspondingly programmed. If a function is activated or if a relay is allocated both settings (Offset 1 and Offset 2) are initially at "OFF". Work can be carried out with one as well as with both limit indicators.		
Limits	_ _"Offset 1" for alarm in case of an exceeding of the max. deviation between actual and target.		
Offset 2	Switch ON point: actual value = Setpoint +/- offset Swtich OFF point: Actual value by hysteresis under the switch-on point		
	"Offset 2" for alarm in case of an undercutting of the max. deviation between actual and target Switch ON point: actual value = Setpoint +/- offset Swtich OFF point: Actual value by hysteresis over the switch-on point		
Limits	Offset Hysteresis Hysteresis switch-on point: In temperature regulation + / - 10 K, otherwise sensors		
Offset Hyst.		mentrange	
Limits  Offset Delay	Offset Delay Time delay until in Setting range: 0 - Factory setting: 2	ndication through relay and alarm symbol. 120 sec. sec.	



Example for temperature regulation; for other modes of operation settings in corresponding sensor unit.



Example: Setpoint 15.0 °C, Offset +5.0 K, Hysteresis 2.0 K



# 9.12 Timer

## 9.12.1 Timerfunction

The device has a real time clock. The clock is backed up (Gold Cap) and has a reserve of 2 or 3 days after sufficient operation on a voltage supply.

The time and date must be set during start-up operation and when using the real-time clock. The device calculates the weekday based on the date.

In principle, the timer function acts like a digital switch input (timer "On"  $\triangleq$  closed contact at inverting OFF). The same functions can be assigned to the timer switch as the digital inputs("D1 ..D2)".

Function	Description *	Timer ON =		
		(@ Timer Invert. = OFF)		
OFF	No function (factory setting)			
Enable	Enable (remote control) "ON" / "OFF"	Device ON		
(1D)		Device ON		
External error	External fault alarm	<b>F</b> ailtine		
(2D)		Fallure		
Limit	"Limit" ON / OFF			
(3D)	Influences control circuit 1 and control circuit 2 in operation with two control circuits	Limit ON		
E1 / E2 (4D)	Switch over input "E1" / "E2" (for operation with one control circuit)	Signal at E2		
Reset	Complete re-start of the device			
(10D)		Reset		
Max. Speed	Max. Speed Setting Max. Speed "ON" / "OFF"			
(11D) Influences the respectively set value "1. Max. Speed" and "2. Max. Speed" in operation with two control circuits.		Max. Speed ON		
Override Time	Override Time Do not use function for timer (only for digital input).			
(21D)	(21D)			
	For mode speed controller 1.01	1		
Setpoint1/2	Switch over "Set Intern1" / "Set Intern2"	Set Intern2		
(5D)	"Setting External 1" must be at "OFF".	Set Internz		
Setpoint int./ext.	Switch over "Intern" / "Extern"	Set extern		
(6D)				
	For modes as controller (from 2.01.)			
Setpoint1/2 (5D)	Switch over "Setpoint 1" / "Setpoint 2"for control circuit1	Setpoint2		



Function	Description *	Timer ON =		
		(@ Timer Invert. = OFF)		
Setpoint int./ext.	Switch over "Intern" / "Extern"	O stars int Esternal		
(6D)	Possible only for operation with one control circuit!	Setpoint External		
Control/Manual	Switch over "automatic control" / "Speed manual"			
(7D)	Possible only for operation with one control circuit!	Manual mode		
Heating/Cooling	Switch over control function (e.g. "heating" / "cooling")	Devene all atom dand		
(8D)		Reversal standard		
1.Setp+Pband1/2	for control circuit 1: Switch over Setpoint 1/2 and Pband 1/1	First sented size it Ost		
(15D)	When programming this function, "Setting" additionally lists	noint 2 + Phand 2		
	the parameter: "1.Pband2 for control circuit 1."			
	Only active in operation with a second control circuit!			
E1 / E2	The output for control circuit 2 is additionally set to "A2" to			
(4D)	"A1" (regardless of the programmed function for "A1"). The			
	first control circuit has no output for the duration of the switch	Second control circuit to		
	The switch over input "E1" / "E2" as in exercise with one	A1 + A2		
	control circuit is no longer possible.			
2. Setpoint 1/2	for control circuit 2: Switch over "2. Setpoint 1" / "2. Setpoint	Second control circuit		
(9D)	2"	Setpoint 2		
2.Setp+Pband1/2	for control circuit 2: Switch over Setpoint 1/2 and Pband 1/2			
(16D)	When programming this function, "Setting" additionally lists the parameter: "2Pband2 for control circuit 2."	Second control circuit Setpoint 2 + Pband 2		

\* Detailed description @ IO Setup / Digital Inputs "D1" / "D2"

# Example: Programming limitation for output voltage (Limit ON / OFF)





Controller Setup	
IO Setup	
Limits	
Timer	
Autoadressing	
Timer	Press the P-key and set the hours with the UP / DOWN keys, press the P-key to save. Now the minutes flash and can be set with the UP / DOWN keys, press the P-key to
13:05	save.
Time	
Timer	To set the date follow the same method as for "Time". The date setting consists of day, month and year
09.04.13	Example for: 9. April 2013
Date	
	-

# 9.12.3 Automatic summer time

The summertime automatic is factory set to "OFF", i.e. switched off. When the summertime automatic is activated the device automatically switches between daylight saving time and wintertime. "North" = for countries in the Northern Hemisphere.

"South" = for countries in the Southern Hemisphere.

		for Northern Hemi- sphere	for Southern Hemi- sphere
Timer		Timer	Timer
OFF Summertime Auto.	→	North Summertime Auto.	South Summertime Auto.



#### Information

If the summer time automatic is used, the switch over date and the switch over time are identical and unchangeable for both settings.

The time is put forward from 2:00 am to 3:00 am respectively on the last Sunday in March (South put back from 3:00 am to 2:00 am) and put back from 3:00 am to 2:00 am (South put forward from 2:00 am to 3:00 am) on the last Sunday in October.

If other dates for the switch over between summer time and winter time are required, the clock must be changed by hand (manually) on the respective date.



# 9.12.4 Enter switching times

**Two** switching times can be entered for the same function (e.g.  $\boxed{3D}$  = Limit) for each weekday. The menu items are repeated for each weekday with two on- and off-times each. Switching times are not preprogrammed at the factory.

In order to make configuration easier, the same switching times can be made for several days in a block. To prevent unwanted switching times from arising, all should be deleted before programming. To do this, select the block Mo - Su and deactivate all 4 switching times.



#### Be sure to delete all switching times before carrying out complete new settings.

\* If switching times are already programmed for all weekdays "Mon-Sun", press the P key and increase the hours with the ▲ - key until the deactivation appears after "23", display: \_\_\_\_. Then press the P key twice to confirm and delete the switching times.

All programmed switching times are deleted after loading the factory setting or resetting the mode.



# Factory setting without preprogrammed switching times

	Mon-Sun												
	Mon-Fri Sat-Sun												
M	on	Tue Wed			ed	T	hr	Fri		Sat		Sun	
ON1	:	ON1	:	ON1	:	ON1	:	ON1	:	ON1	:	ON1	:
OFF1	:	OFF1	:	OFF1	:	OFF1	:	OFF1	:	OFF1	:	OFF1	:
ON2	:	ON2	:	ON2	:	ON2	:	ON2	:	ON2	:	ON2	:
OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:

Example	xample 1: Every day at 8 am ON and at 6 pm OFF												
	Mon-Sun												
ON1	08:00	ON1	08:00	ON1	08:00	ON1	08:00	ON1	08:00	ON1	08:00	ON1	08:00
OFF1	18:00	OFF1	18:00	OFF1	18:00	OFF1	18:00	OFF1	18:00	OFF1	18:00	OFF1	18:00
ON2	:	ON2	:	ON2	:	ON2	:	ON2	:	ON2	:	ON2	:
OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:

Example	Example 2: Monday to Friday at 6 am ON at 8 am OFF and at 5 pm ON at 10 pm OFF												
	Mon-Fri									Sat-Sun			
ON1	06:00	ON1	06:00	ON1	06:00	ON1	06:00	ON1	06:00	ON1	:	ON1	:
OFF1	08:00	OFF1	08:00	OFF1	08:00	OFF1	08:00	OFF1	08:00	OFF1	:	OFF1	:
ON2	17:00	ON2	17:00	ON2	17:00	ON2	17:00	ON2	17:00	ON2	:	ON2	:
OFF2	22:00	OFF2	22:00	OFF2	22:00	OFF2	22:00	OFF2	22:00	OFF2	:	OFF2	:

Example	Example 3: Wednesday 6 pm ON and Thursday at 8 am OFF												
Mon Tue		le	Wed		Thr		Fri		Sat		Sun		
ON1	:	ON1	:	ON1	18:00	ON1	:	ON1	:	ON1	:	ON1	:
OFF1	:	OFF1	:	OFF1	:	OFF1	08:00	OFF1	:	OFF1	:	OFF1	:
ON2	:	ON2	:	ON2	:	ON2	:	ON2	:	ON2	:	ON2	:
OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:

Free tab	Free tables for entering individual timer settings								
M	on	Tue	e We	ed T	hr F	ri S	at S	un	
ON1		ON1	ON1	ON1	ON1	ON1	ON1		
OFF1		OFF1	OFF1	OFF1	OFF1	OFF1	OFF1		
ON2		ON2	ON2	ON2	ON2	ON2	ON2		
OFF2		OFF2	OFF2	OFF2	OFF2	OFF2	OFF2		



### 9.12.5 Inverting timer function

Inverting of the timer function is possible if required.

Timer	Timer Inverting
OFF Timer Inverting	In the "OFF" setting (factory setting), the programmed function is activated at the switch-on time (clock icon in the display) and deactivated again at the switch-off time (@ timer function).
	In the "ON" setting, the programmed function is deactivated at the switch-on time and activated again at the switch-off time (clock icon in the display).

### 9.12.6 Overwrite timer function

The timer output can be overwritten for a settable time with a selectable status if required. Activation is by a digital input ( $\Im$  IO Setup function 21D)

Application: Exceptions from the normal timing operation, e.g. for manual or automatic presence switch, party mode, etc.

Timer	Override Time
120 min Override Time	Settable time for overwriting the timer function Setting range: 065535 min. Factory setting: 120 min
	In the "0 min." setting, the timer function is overwritten with the selected status until the next timing change.
Timer	Override Status
	Settable status when overwriting the timer function:
OFF	ON = function as for timer ON @ timer function
Override Status	OFF = function as for timer OFF (factory setting)

## 9.12.7 Adjustment of the real time clock

Timer	Fine adjustment of the real time clock is possible if required.
60 RTC Adjust	The greater the value, the slower the clock runs. If the value is increased by one point, this corresponds to a slowing of the clock by approx. 2 to 3 s per month. Setting range: 0 - 127 Factory setting: 60

## 9.13 MODBUS Slave

Addressing and configuration of the MODBUS Slave interface.

Via this interface the device can be networked with a master building control system, the device then operates as a pure Slave and uses the MODBUS-RTU protocol.

The connection is made to the terminals "2A (2D+)", "2B (2D-)" of the MODBUS Slave interface ( rate installation / RS-485 interfaces for MODBUS RTU).



#### Information

- In the IO Setup the "COM function must be set" to "MODBUS Slave" so that this menu group is displayed (factory setting).
- MODBUS settings (baud rate, parity) are saved after a reset ( menu group "Start" -> "Reset" or interrupt voltage supply).



MODBUS Slave	Bus Address
	The device address is factory set to the highest available MODBUS address: 247.
247	Setting range MODBUS Address: 1 - 247.
Bus Address	
MODBUS Slave	Addressing
	Switch addressing to "ON" before setting "address".
OFF	
Addressing	
MODBUS Slave	UART Baudrate
	Setting transfer rate
19200	Valid values: 4800, 9600, 19200, 38400, 115200
UART Baudrate	Factory setting: 19200
MODBUS Slave	UART Mode
	Setting transfer format
8E1	Valid values: 8O1, 8N1, 8E1
UART Mode	Factory setting: 8E1

# 9.14 MODBUS Master

Addressing of the members that are activated via the MODBUS Master interface. Addressing can be done automatically by a patented method. It is then no longer necessary to address every single member manually in the network.

Alternatively, manual addressing is possible, for which separate components are required for setting the individual member address.



# Information

- A maximum of 32 devices can be connected. The communication settings are pre-set to 19.2kbd, 8E1 and cannot be changed.
- To ensure activation, the function of the digital input "D1" of the members is automatically set to "OFF" by the MODBUS Master. I.e. any programmed enable function for switching off the member (by a potential-free contact) is no longer active.

Main menu		MODBUS Master	
MODBUS Master		After addressing (manual or automatic), the devices are subsequently listed to the	
Fan 1 (2A)		/IODBUS Master" menu group (@""members MODBUS Master").	
Fan 2 (2A)			
Fan 3 (2A)			
[P] Enter	[ESC] Info		





#### 9.14.1 Automatic addressing

- The first member (MODBUS address 1) must be connected to the terminals 1A(1D+) and 1B (1D-), additionally the "ID" connections must be connected ( ID" installation / communication / addressing members MODBUS Master interface).
- The members are automatically addressed consecutively according to the installation.
- In order to do the automatic addressing successfully, all the bus members to be addressed must be connected with each other, applied to voltage and switched on.

#### The automatic addressing can only be done with compatible devices!

Main menu	MODBUS Master
Limits	
Timer	
Diagnostic	
MODBUS Master	
[P] Enter [ESC] Info	
MODBUS Master	1. <b>Press the P-key</b> to open the "MODBUS Master".
	2. <b>Press the P-key</b> to select automatic addressing.
Autoaddressing	3. <b>Press the P-key</b> to start automatic addressing.
[P] Enter [ESC] Menu	
MODBUS Master	Display while the automatic addressing is in progress.
Addressing Found: 0 In progress	
[P] Repeat [ESC] Cance	
MODBUS Master	The found members count is displayed at the end of automatic addressing.
Addressing Found: 5 Done [P] Repeat [ESC] Cance	Press the <b>P-key</b> again to repeat the addressing. Exit the menu with the Esc key combination <b>▼</b> + ▲.



## 9.14.2 Manual addressing

The addressing is done manually by a separate hand held terminal or PC software, the corresponding member count must be entered on the MODBUS Master.

- The members are connected to the device by the terminals 1A(1D+) and 1B (1D-) ( installation / communication).
- All bus members must be addressed uniquely, consecutively and starting at address **1**. Otherwise communication could be disturbed or no communication can be set up.
- In order to complete the manual addressing successfully, all the bus members to be addressed must be connected with each other, applied to voltage and switched on.

Main menu	MODBUS Master
Limits	
Timer	
Diagnostic	
MODBUS Master	
[P] Enter [ESC] Info	
MODBUS Master	Press the P-key to open the "MODBUS Master".
Autoaddressing	
[P] Enter [ESC] Menu	
MODBUS Master	Press the ▼-key to select the "Bus Slavecount" menu.
0	
Bus Slavecount	
[P] Edit [ESC] Menu	
MODBUS Master	Press the P-key to open the menu.
	Set the correct member count with the $\mathbf{\nabla} \mathbf{A}$ keys and confirm with the <b>P-key</b> .
5	Exit the menu with the Esc key combination ▼ + ▲.
Bus Slavecount	
[P] Edit [ESC] Menu	

Info	Error message when entering too high a member count, alternately with the actual
Error MODBUS Com Fan: 2	value display.





# 9.15 Member MOBUS Master

After addressing, (manual or automatic) the members are then listed to the "MODBUS Master" menu group.

Main menu		The function for activation by MODBUS is displayed after the address of the
MODBUS Master		member.
Fan 1 (2A)		The same function is programmed initially for all members after addressing. 1.
Fan 2 (2A)		Control Signal (2A)].
Fan 3 (2A)		I.e. every member is activated by the output of control circuit 1.
[P] Enter	[ESC] Info	

After selection with the  $\checkmark$   $\blacktriangle$  keys, press the **P-key** to open the State menu of the member (menu content depends on the type of member).

#### State menu member Example: ECblue fan

Fan 1 (2A)							
ECblue V13.05	← Device type and firmware version						
Fan OK!	- Operating state of the member						
Speed [rpm 570]	← Speed Actual value (1/min)						
Motorcurrent [A] 2.60	← Current consumption						
P=0W Level=0%	← Power consumption and modulation of the device						
[P] Edit [ESC] Menu							

To set the MODBUS function for the member, press the **P-key**.

Fan 1 (2A)	Press the P-key to open the menu.
1st control signal	Select the desired MODBUS function with the $\blacksquare$ keys and save with the <b>P-key</b> .
(2A)	Pre-programmed function 1. Control Signal (2A) = output of control circuit 1.
MB Function	For example, to activate speed controllers for fans or fans with integrated con-
[P] Edit [ESC] Menu	The programmable functions correspond to the functions for the analogue outputs (P IO Setup).
	<ul> <li>For members activated by control circuit 2, function: [2. Control Signal (8A)]</li> <li>For members activated in groups (function: [5A], [11A], [12A]), the "Group Version" setting must be observed, at factory setting "OFF" there is no activation (P Controller Setup)!</li> </ul>

Exit the menu with the Esc key combination  $\mathbf{\nabla} + \mathbf{\Delta}$ .



# **10** Menu tables

# 10.1 Menues of operating modes

Mode	1.01 1.02	2.01 2.03 2.04	2.02	2.05	3.01 3.02	3.03 3.04	4.01 4.02 4.03	5.01 5.02	6.01	User Setting
Parameter			I	Fa	ctory sett	ing		1		
		[	[	1	Info			1	1	
Setting direct	1.02 = 80 %									
Setting step <sup>1</sup>	1.02 = 0									
E1-E2 actual				-2.4 °C						
Control value		2.04 = 30.0 °C				12.0 bar 22.6 °C				
E1 Actual		30.0 °C	30.0 °C	30.0 °C	10.0 bar -88.7 °C	10.0 bar -88.7 °C	88.7 Pa	712 m <sup>3</sup> h	0.45 m/s	
E2 Actual		2.04 = 30.0 °C		30.0 °C		10.0 bar -88.7 °C	4.02, 4.03 = 21.0 °C	5.02 = 21.0 °C		
Setpoint1 1.Setpoint 1 <sup>2</sup>		20.0 °C	5.0 °C	0.0 °C	12.0 bar 35.0°C	12.0 bar 35.0°C	100 Pa	530 m <sup>3</sup> h	0.50 m/s	
2.Setpoint 1 <sup>3</sup>										
Setpoint control							4.02, 4.03 = 100 Pa	5.02 = 530 m <sup>3</sup> h		
Modulation 1. Control <sup>2</sup>	1.01 = 0 %	0 %	0 %	0 %	0 %	0 %	0 %	0 %	0 %	
1. Control <sup>3</sup>		0 %	0 %		0 %	0 %	0 %	0 %	0 %	
Set external1	1.01 = 0 %									
Min. speed cut off 1. Min. speed cut off <sup>2</sup>		OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
2. Min. speed cut off <sup>3</sup>										
				1	Start			1	1	
PIN input										
Language	GB	GB	GB	GB	GB	GB	GB	GB	GB	
US units	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Mode	1.01 1.02	2.01 2.03	2.02	2.05	3.01 3.02	3.03 3.04	4.01 4.02	5.01 5.02	6.01	
	0.31	2.04	0.31	0.31	0.31	0.31	4.03	0.31	0.31	
SN:	000005- E45536	000005- E45536	000005- E45536	000005- E45536	000005- E45536	000005- E45536	000005- E45536	000005- E45536	000005- E45536	
				_ 10000	_ 10000			_ 10000	_ 10000	I
				5	Setting					
Set Intern1	1.01 = 80%									
Set Intern2	1.01 =									
Setting direct	1.02 = 80%									



Mode	1.01 1.02	2.01 2.03 2.04	2.02	2.05	3.01 3.02	3.03 3.04	4.01 4.02 4.03	5.01 5.02	6.01	User Setting
Parameter			L	Fa	ctory sett	ing		1	L	
Setting step <sup>1</sup>	1.02 = 0									
Setpoint1 1.Setpoint 1 <sup>2</sup>		20.0 °C	5.0 °C	0.0 °C	12.0 bar 35.0°C	12.0 bar 35.0°C	100 Pa	530 m <sup>3</sup> h	0.50 m/s	
Setpoint2 1.Setpoint 2 <sup>2</sup>							4.03 = 100 Pa			
Pband 1 1. Pband 1 <sup>2</sup>		5.0 K	20.0 K	5.0 K	5.0 bar 7.0 K	5.0 bar 7.0 K	100 Pa	530 m <sup>3</sup> h	0.50 m/s	
1. Pband 2 <sup>4</sup>		5.0 K	20.0 K	5.0 K	5.0 bar 7.0 K	5.0 bar 7.0 K	100 Pa	530 m <sup>3</sup> h	0.50 m/s	
Min. Speed 1.Min. Speed <sup>2</sup>	0%	0%	0%	0%	0%	0%	0%	0%	0%	
Max. Speed 1. Max. Speed <sup>2</sup> 2. Setpoint 1 <sup>3</sup>	100 %	100 %	100 %	100 %	100 %	100 %	100 %	100 %	100 %	
2.Setpoint 2 <sup>3</sup> 2. Pband 1 <sup>3</sup>										
2. Pband 2 <sup>5</sup>										
2. Min. Speed <sup>3</sup>	0%	0%	0%		0%		0%	0%	0%	
2. Max. Speed <sup>3</sup>	100 %	0%	100 %		100 %		100 %	100 %	100 %	
Set external1	1.01 = ON									
Manual mode 1. Manual mode <sup>2</sup>		OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Speed manual 1. Speed man. <sup>2</sup>		100 %	100 %	100 %	100 %	100 %	100 %	100 %	100 %	
Offset AnalogOut		2.03 = 0.0 K								
Pband AnalogOut		2.03 = 2.0 K								
Min. AnalogOut		2.03 = 0 %								
Max. AnalogOut		2.03 = 100 %								
OffsetDigitalOut		2.03 = - 1.0 K								
Hyst.DigitalOut		2.03 = 1.0 K								
Alarm Minimum		2.03 = 0.0 °C								
Alarm Maximum		2.03 = 40.0 °C								
T-Band SA							4.02 + 4.03 = 30.0 K	5.02 = 30.0 K		
T-Start SA							4.02 + 4.03 = 15.0 °C	5.02 = 15.0 °C		
Min Setpoint							4.02 + 4.03 = 70.0 Pa	5.02 = 700 m <sup>3</sup> h		
				Р	rotocol					
1	1	1	1	1	1		1	1	1	



Mode	1.01 1.02	2.01 2.03 2.04	2.02	2.05	3.01 3.02	3.03 3.04	4.01 4.02 4.03	5.01 5.02	6.01	User Setting
Parameter		1		Fa	ctory sett	ing		1	I	
				_						
Mode	1.01 1.02	2.01 2.03 2.04	2.02	2.05	3.01 3.02	3.03 3.04	4.01 4.02 4.03	5.01 5.02	6.01	
E1 Analog In	1.01 = 0 - 10 V	TF	TF	TF	0-30 MBG	0-30 MBG	DSG200	4.01 = DSG200 4.02 + 4.03 = DSG50	0-1 MAL	
Number steps	1.02 = 0									
Step 1 value	1.02 = (20%)									
Step 2 value	1.02 = (40%)									
Step 3 value	1.02 = (50%)									
Step 4 value	1.02 = (60%) 1.02 =									
Step 5 value	(100%)									
E1 Refrigerant					3.02 = R503	3.04 = R503				
E1 K-Factor E1 Unit								75		
E1 Decimals										
E1 Min.										
E1 max										
E1 Offset		149.9 °C	149.9 °C	149.9 °C	0.00 bar 149.9 °C	0.00 bar 149.9 °C	0.0 Pa	0 m <sup>3</sup> h	0.0 m/s	
E2 Function	1.01 = OFF	OFF 2.04 = 4E	OFF	5E	OFF	4E	OFF 4.02 + 4.03 = 6E	OFF 5.02 = 6E	OFF	
E2 Analog In	1.01 =	2.04 = TF		TF		0-30 MBG	4.02 = TF 4.03 = Bus	5.02 = TF		
E2 Refrigerant						3.04 = R503				
E2 K-Factor <sup>2</sup>										
E2 Unit							4.03 = °C			
E2 Decimals							4.03 = 1			
E2 Min.							4.03 = - 35.0 °C			
E2 Max.							4.03 = 65.0 °C			



Mode	1.01 1.02	2.01 2.03 2.04	2.02	2.05	3.01 3.02	3.03 3.04	4.01 4.02 4.03	5.01 5.02	6.01	User Setting	
Parameter				Fa	ctory sett	ing					
E2 Offset		2.04 = 149.9 °C		149.9 °C		0.00 bar 149.9 °C	4.02 + 4.03 = 149.9 °C	5.02 = 149.9 °C			
Controller Setup											
PIN Protection	OFF	OFF	OFF	OFF			OFF	OFF	OEE		
Sat protection	011	055	011	OFF		OFF	OFF		011		
Set protection	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF		
Alarm concore	OFF										
Limit		ON	ON	ON	ON	ON	ON	ON	ON		
Min speed cut off											
1. Min. speed cut off <sup>2</sup>		OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF		
2. Min. speed cut off <sup>3</sup>											
Val>Set=n+ 1. Val>Set=n+ <sup>2</sup>		ON	ON	ON	ON	ON	OFF	OFF	OFF		
2. Val>Set=n+ <sup>3</sup>											
Type of control 1.Controller type <sup>2</sup>		Р	Р	Р	Р	Р	Pid	Pid	Pid		
2.Controller type <sup>3</sup>											
KP		50 %	50 %	50 %	50 %	50 %	50 %	50 %	50 %		
КІ		50 %	50 %	50 %	50 %	50 %	50 %	50 %	50 %		
KD		50 %	50 %	50 %	50 %	50 %	50 %	50 %	50 %		
TI		0 %	0 %	0 %	0 %	0 %	0 %	0 %	0 %		
Group version	0	0	0	0	0	0	0	0	0		
Group 2 ON value											
OFF Value Group2											
nmin at Group2											
Group 3 ON value											
OFF Value Group3											
nmin at Group3											
Group 4 ON value											
OFF Value Group4											
nmin at Group4											
External message	0.0/	0.0/	E	xternal erro	or	0.0/	0.0/	0.00	0.0/		
	0 %	0 %	0 %	0 %	0%	0%	0 %	0 %	0 %		
Selection amplifier		OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF		
				IC	) Setup						
A1 Function	2A	2A	2A	2A	2A	2A	2A	2A	2A		
A1 min.	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V		
A1 max.	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V		
A1 Inverting	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF		
A2 Function	1A	1A (2.03 = 6A)	1A	1A	1A	1A	1A	1A	1A		
A2 min.	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V	0.0 V		
A2 max.	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V	10.0 V		



Mode	1.01 1.02	2.01 2.03 2.04	2.02	2.05	3.01 3.02	3.03 3.04	4.01 4.02 4.03	5.01 5.02	6.01	User Setting
Parameter				Fa	ctory sett	ing		1	1	
A2 Inverting	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
D1 Function	OFF	OFF	OFF	OFF	OFF	OFF	OFF 4.03 = 1D	OFF	OFF	
D1 Inverting							4.03 = OFF			
D1 Busmode							4.03 = ON			
D2 Function	OFF	OFF	OFF	OFF	OFF	OFF	OFF 4.03 = 5D	OFF	OFF	
D2 Inverting							4.03 = OFF			
D2 Busmode							4.03 = ON			
D - D Relation	OG	OG	OG	OG	OG	OG	OG	OG	OG	
E1 Inverting	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
E1 Busmode	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
E2 Inverting		2.04 = OFF		OFF		OFF	4.02 + 4.03 = OFF	5.02 = OFF	OFF	
E2 Busmode	OFF	OFF	OFF	OFF	OFF	OFF	OFF 4.03 = ON	OFF	OFF	
K1 Function	1K	1K (2.03 = 2K)	1K	1K	1K	1K	1K	1K	1K	
K1 Inverting	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
K2 Function	2K	2K (2.03 = 9K)	2K	2K	2K	2K	2K	2K	2К	
K2 Inverting	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
COM2 Function				MC	DDBUS Sla	ave				
	1	1			Limits	I	T	1	T	
Level Function 1. Level. Function <sup>2</sup>	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Level min. 1. Level min. <sup>2</sup>										
Level max. 1. Level max. <sup>2</sup>										
Level Delay 1. Level Delay <sup>2</sup>										
Lmt E1 Function	OFF	OFF 2.03 = 1L	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Lmt E1 min		2.03 = 0.0 °C								



Mode	1.01	2.01 2.03	2.02	2.05	3.01	3.03	4.01 4.02	5.01	6.01	User Setting
<b>D</b>	1.02	2.04			0.02	0.04	4.03	0.0E		-
Parameter Factory setting										
Lmt E1 max.		2.03 = 40.0 °C								
Lmt E1 Hyst.		2.03 = 1.0 K								
Lmt E1 Del.		2.03 = 2 sec.								
Lmt E2 Function		2.04 = OFF		OFF		OFF	4.02,03 = OFF	5.02 = OFF		
Lmt E2 min.										
Lmt E2 max.										
Lmt E2 Hyst.										
Lmt E2 Del.										
Offset Function 1. Offset Function <sup>2</sup>		OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Offset 1 1.Offset 1 <sup>2</sup>										
Offset 2 1.Offset 2 <sup>2</sup>										
Offset Hyst. 1. Offset Hyst. <sup>2</sup>										
Offset Delay 1. Offset Del. <sup>2</sup>										
					Timor					
Time	14.24	14.24	14.24	14.24	14.24	14.24	14.24	14.24	14.24	
Date	19.0/ 13	19.0/ 13	19.0/ 13	19.0/ 13	19.0/ 13	19.0/ 13	19.0/ 13	19.0/ 13	19.0/ 13	
Summertime Auto.	0FF	0FF	0FF	0FF	0FF	0FF	0FF	0FF	0FF	
Timer Function	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Mon	011	011	011	011	011	011	011	011	011	
Mon ON1	:	:	:	:	:	:	:	:	:	
Mon OFF1	:	:	:	:	:	:	:	:	:	
Mon ON2	:	:	:	:	:	:	:	:	:	
Mon OFF2	:	:	:	:	:	:	:	:	:	
RTC Adjust	60	60	60	60	60	60	60	60	60	
Timer Inverting	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Override Time	120 min	120 min	120 min	120 min	120 min	120 min	120 min	120 min	120 min	
Override Status	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
Runtime Controller	000056:-	000056:-	000056:-	Dia 000056:-	agnostic 000056:-	000056:-	000056:-	000056:-	000056:-	
	40.13	40.13	40.13	40.13	40.13	40.13	40.13	40.13	40.13	
Runtime Motor	46:13	46:13	46:13	46:13	46:13	46:13	46:13	46:13	46:13	
	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	
E1-Current	0.00 mA	0.00 mA	0.00 mA	0.00 mA	0.00 mA	0.00 mA	0.00 mA	0.00 mA	0.00 mA	
	0.00 V	0.00 V	0.00 V	0.00 V	0.00 V	0.00 V	0.00 V	0.00 V	0.00 V	
	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0 °C	20.0°C	20.0°C	20.0 °C	
E2-Current	0.00 mA	0.00 mA	0.00 mA	0.00 mA	0.00 mA	0.00 mA	0.00 mA	0.00 mA	0.00 mA	





Mode	1.01 1.02	2.01 2.03 2.04	2.02	2.05	3.01 3.02	3.03 3.04	4.01 4.02 4.03	5.01 5.02	6.01	User Setting
Parameter				Fa	ctory sett	ing				
E2 - Voltage	0.00 V	0.00 V	0.00 V	0.00 V	0.00 V	0.00 V	0.00 V	0.00 V	0.00 V	
D1	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
D2	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
К1	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
К2	ON	ON	ON	ON	ON	ON	ON	ON	ON	
	1	T	T	MOD	BUS Slav	е	T	1	T	1
Bus Address	247	247	247	247	247	247	247	247	247	
Addressing	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF	
UART Baudrate	19200	19200	19200	19200	19200	19200	19200	19200	19200	
UART Mode	8E1	8E1	8E1	8E1	8E1	8E1	8E1	8E1	8E1	
									·	
MODBUS Master										
Autoaddressing										
Bus Slavecount	0	0	0	0	0	0	0	0	0	

1 For adjustment "Setting Sep" > 0 ( Base setup)

For control circuit 1 in operation with a second control circuit (P Base Setup / Function E2)
 For control circuit 2 in operation with a second control circuit (presetting depending on programmed function)

4 In operation with control circuit 2 and programmed function 15 D for digital input ( I Setup)

5 In operation with control circuit 2 and programmed function 16 D for digital input (@ IO Setup)



# 10.2 Possible allocation of the IOs, PINs

# Units for analog inputs E1 and E2

The following units can be set for programmed sensors with free measuring range (0 - 10 V, 0 - 20 mA, 4 - 20 mA).				
E1 Analog In *	°C, m³/h, bar, %, Pa, m/s, m³/s, Ohm, mbr, °F, ft/s, cfm, in.wg, psi, ppm			
E2 Analog In				

\* for Modes **5.01** and **5.02** display in m<sup>3</sup>/h, other units are not possible

# Analog outputs A1 and A2

Function	Description
OFF	no function
Constant voltage 10 V	Constant voltage +10 V
(1A)	Factory setting for "A2" at operation with one control circuit.
1st control signal	Controlled 0 - 10 V output for control circuit 1 (factory setting for "A1")
(2A)	
E1	proportional input "E1"
(3A)	
E2	proportional input "E2"
(4A)	
Group2	Group control ( Controller Setup - group 2)
(5A)	
2.Cooling	Only for mode <b>2.03</b> temperature controller with additional functions.
(6A)	Controller output 2 with rising activation at Actual>Nominal = <b>Cool</b> .
2.Heating	Only for mode <b>2.03</b> temperature controller with additional functions.
(7A)	Controller output 2 with rising activation at Actual <nominal =="" heat.<="" th=""></nominal>
2. control signal	Controlled 0 - 10 V output vor control circuit 2.
(8A)	Factory setting for "A2" at operation with second control circuit.
	A second control circuit can be activated if required by programming the E2 function ( Base Setup E2 functions 8E - 13E and second control circuit)
Speed	proportionally 1.Control signal
(9A)	
Group3	Group control (@ Controller Setup - group 3)
(11A)	
Group4	Group control (@ Controller Setup - group 4)
(12A)	
Offset control sig. 1	Offset control signal 1
(14A)	Setting offset @ Controller Setup



# Digital inputs D1 and D2

Function	Description
OFF	No function (factory setting)
Enable (1D)	Enable (remote control) "ON" / "OFF"
External error (2D)	External fault alarm
Limit	"Limit" ON / OFF
(3D)	Influences control circuit 1 and control circuit 2
E1 / E2 (4D)	Switch over input "E1" / "E2" (for operation with one control circuit)
Reset (10D)	Complete re-start of the device
Max Speed	Setting Max. Speed "ON" / "OFF"
(11D)	Influences the respectively set value "1. Max. Speed" and "2. Max. Speed" in operation with two control circuits.
Override Time (21D)	Overwrite timer function (in operation with timer)
	For Mode Speed controller 1.01
Setpoint1/2	Switch over "Set Intern1" / "Set Intern2"
(5D)	"Setting External 1" must be at "OFF".
Setpoint int./ext. (6D)	Switch over "Intern" / "Extern"
	For modes as controller nigner ZUI
Setpoint1/2 (5D)	Switch over Setpoint 1 / Setpoint 2 for control circuit i
Setpoint int./ext.	Switch over "Intern" / "Extern"
(6D)	Possible only for operation with one control circuit!
Control/Manual	Switch over "automatic control" / "Speed manual"
(7D)	Possible only for operation with one control circuit:
Heating/Cooling (8D)	Switch over control function (e.g. "neating"/"cooling")
1 Setn+Phand1/2	for control circuit 1: Switch over Setpoint 1/2 and Pband 1/1
(15D)	When programming this function, "Setting" additionally lists the parameter: "1.Pband2 for control circuit 1."
	Only active in operation with a second control circuit!
E1 / E2	programmed function for A1). The first control circuit has no output for the duration of the switch over.
(4D)	The switch over input "E1" / "E2" as in operation with one control circuit is no longer possible.
2. Setpoint 1/2 (9D)	for control circuit 2: Switch over "Setpoint 1" / "Setpoint 2"
2.Setp+Pband1/2 (16D)	for control circuit 2: Switch over Setpoint 1/2 and Pband 1/2 When programming this function, "Setting" additionally lists the parameter: "2Pband2 for control circuit 2."



# Analogue input E2

Function	Description Function E2						
OFF	No function (factory setting)						
For mode speed controller 1.01							
1E	Operation with a second setting signal (switch over "E1" <-> "E2" via floating contact)						
4E	Operation with a second setting signal and automatic control at the higher level ("E1" <- > "E2")						
	For modes as controller higher 2.01						
Ext. Setpoint (1E)	1E = External Setpoint e.g. via external signal (0 - 10 V) instead of "Setpoint 1"						
Ext. Manual mode (2E)	External manual operation via external signal (0 - 10 V). Switch over between settings on the device and external manual operation via digital input.						
Average E1 (3E)	Sensor average with E1 (@mode 2.04)						
Comparison E1 (4E)	Sensor comparison with E1 (@mode 2.04)						
Difference E1 (5E)	Sensor difference to E1 (@mode 2.05)						
Setpoint derating (6E)	Sensor for setpoint outdoor temperature controlled ( mode 4.02, 5.02).						
Measurement (7E)	Measurement value e.g. Measurement value e.g. for limit indication, display in Info menu "E2 Actual".						
	For activation of a second control circuit						
(Only Temperature	possible in certain modes ( ) operation with second control circuit )						
(8E)	Temperature control, pre-settings and sensor selection correspond to mode <b>2.01</b>						
Cold-Pressure (9E)	Pressure control condensers, pre-settings and sensor selection correspond to mode <b>3.01</b>						
Cold-Temperature (10E)	Pressure control condensers with input for refrigerant, pre-settings, sensor selection and input for refrigerant corresponding to mode <b>3.02</b>						
Air Pressure (11E)	Pressure control air conditioning, pre-settings and sensor selection correspond to mode <b>4.01</b>						
Air flow (12E)	Volume control, pre-settings, sensor selection and K-factor for inlet ring correspond to mode <b>5.01</b>						
Air speed (13E)	Air velocity control, pre-settings correspond to mode 6.01						



# Digital outputs K1 and K2

Function	Description
OFF	No function
	Relays remain always de-energized
Operating indication	Operating indication (factory setting for "K1", non inverting).
(1K)	Operation without fault, reports enable "OFF"
Fault indication	Fault indication (factory setting for "K2", non inverting).
(2K)	Pulled up in operation without fault, with release "OFF" not dropped out.
	Drops out in case of line and device fault and external fault at the digital input. Depend-
	ing on programming in event of sensor failure.
External error	External fault separate with message at digital input (factory setting if terminals
(3K)	bridged)
Limit modulation	Limit modulation
(4K)	Over or falling below limits for modulation
Limit E1	Limit "E1"
(5K)	When over or falling below limits for input signal "E1"
Limit E2	Limit "E2"
(6K)	When over or falling below limits for input signal "E2"
	For modes as controller higher 2.01
Setpoint Offset	Setpoint Offset
(7K)	Deviation between actual value and setpoint to high
Group2	Group control (Group 2)
(8K)	Switching on fans depending on modulation
Group3	Group control (Group 3)
(12K)	Switching on fans depending on modulation
Group4	Group control (Group 4)
(14K)	Switching on fans depending on modulation
For	modes as temperature controller with additional functions <b>2.03</b>
2.Heating	Heating function
(9K)	Switch ON point: temperature = Setpoint +/- Offset
	Switch OFF point: Temperature around hysteresis over switch ON point
2.Cooling	Cooling function
(10K)	Switch ON point: temperature = Setpoint +/- Offset
	Switch OFF point: Temperature around hysteresis below switch ON point

# Limits GW E1 and GW E2

Function	Description function GW E1, GW E2
OFF	no function
Failure	Indication with the centralized fault of a programmed relay (IO allocation Function [2K]).
(1L)	Warning symbol in display, "AL" code in events memory.
Message	Is merely displayed in the events menu as message "msg".
(2L)	
Filter error	Like function 1L with fault message "Filter"
(3L)	
Filter Message	Like function 2L with fault message "Filter"
(4L)	





# PINs

PIN	Function
PIN 0010	Opening service menu, if PIN-protection activated
PIN 1234	Opening "setting".
	If set protection = ON ( Controller Setup)
PIN 9090	Restore user setting
PIN 9091	Save user setting (corresponds function "Save user setup" = "ON" @ Controller Setup)
PIN 9095	Restore factory setting = delivery status

# 11 Diagnostics menu

Main menu	The diagnostics menu supplies information about the momentary operating condition
IO Setup	of the device.
Limits	
Timer	
Autoaddressing	
Diagnostic	
Diagnostic	Operating hours on the line
000419:27:28 Runtime Controller	The time counter (h:m:s) runs as soon as line voltage is applied to the device and the device is switched on (without failure). If events occur (e.g. sensor failure, MODBUS communication etc.), the operating time at this time is also saved (@ Protocol).
Diagnostic	Operating hours with modulation
Diagnostic	The time counting (h:m:s) runs only when a modulation of the controller is present
000146-23-54	
Runtime Motor	
Diagnostic	Signal height at analog input F1 (Analog In 1)
Blaghoollo	
20.0 °C	
E1 - KTY	
Diagnostic	
Blaghoollo	
9.0 mA	
F1-Current	
Erounom	-
Diagnostic	
4.0 V	
E1 - Voltage	
Diagnostic	Signal height at analog input E2 (Analog In 2)
20.0 °C	
E2 - KTY	
Diagnostic	
9.0 mA	
E2-Current	



Diagnostic	
4.0 V E2 - Voltage	
Diagnostic	Status digital input 1 (Digital In 1)
OFF D1	ON = terminals D1 - 24V bridged ↔ OFF = terminals D1 - 24V not bridged
Diagnostic	Status digital input 2 (Digital In 2)
OFF D2	ON = terminals D2 - 24V bridged ↔ OFF = terminals D2 - 24V not bridged
Diagnostic	OFF = relay K1 de-energized: terminals 11 - 12 bridged
ON K1	ON = relay K1 energized: terminals 11 - 14 bridged
Diagnostic	OFF = relay K2 de-energized: terminals 21 - 22 bridged
OFF K2	



# 12 Protocol

12.1	Display and	query of	fevents and	malfunctions
------	-------------	----------	-------------	--------------

Main menu	Events during operation can lead to a malfunctioning of the device.
Start	The last 100 events are saved in the "Protocol" menu group.
Setting	Position 1 = latest event, display: Protocol 1/100
Protocol	Position 100 = last saved event, display: Protocol 100/100
Base setup	
Controller Setup	The saved events are retained even after resetting to factory setting (@menu group Start / PIN input)!

The device distinguishes between several event types which are identified by different symbols.

# Example

Protocol 1/100	Attention symbol = message			
Modulation	The message is only listed in the protocol. There is no message alternately with the actual value display and no message via alarm relay.			
Runtime Controller	Exception			
000493:04:59	n case of sensor failure there is always a message in the display (@ Controller Setup / Alarm Sensors).			
Protocol 2/100	Bell symbol = Alarm			
Error MODBUS Com Buntime Controller	The alarm message is listed in the protocol and appears alternately with the actual value display.			
000193:04:59	Message by alarm relay depending on the type of failure and programming.			
Protocol 2/100	Cross symbol = previous messages			
Line Fault	Cause of the message no longer exists.			
Runtime Controller				
000493:04:59				

## Example: Previous line failure on a member

Protocol 2/100	X	
Line Fault Runtime Controller 000493:04:59		Previous line failure on a member connected via the MODBUS interface. When the failure was cleared (line voltage available again), the device was on the line for 493 hours, 4 minutes and 59 seconds.
[P] Details [ES	C]Menu	

# Press the P-key to show further details.

Protocol 2/10	0 🗙	
Line Fault		Date and time when the failure was cleared (time setting @ timer)
Date	Time	
15.04.13	10:24	
[P] Details	[ESC]Menu	



Press the P-key to show further details.

Protocol 2/100	X	
Line Fault		Member on which the failure occurred.
Fan 1		
[P] Details	[ESC]Menu	

Press the P-key to show further details.

Protocol 2/100	X	
Line Fault Modulation		Modulation of the member at the time of the message.
0 %		
[P] Details	[ESC]Menu	

Exit the menu with the Esc key combination  $\nabla + \blacktriangle$ .

# 12.2 Messages and trouble shooting

A momentary pending alarm or error message is indicated by a blinking display and appears alternately with the actual value display.

Relais switches *		Cause	Reaction of Controller	
Opera- tion	Failure		Adjustment	
 No line voltage Jumper J1 for USB interfact plugged		Line voltage available? Unit switch OFF and automatically ON when the voltage has been re- stored Check line fuse Check jumper J1, pull off or only plug to one PIN		
х	-	No enable	Switch OFF by external contact (function 1D = enable programmed for Digital In)	
-	-	fault in Eprom	Norks with defaults.	
-	Х	fault EEP damaged	Works with defaults.	
х	х	EEP data incorrectly	controller runs with the read settings.	
-	Х	Sensor 1 Interruption / short circuit in the sensor leads or sensor values measured are out- side measuring range	The device works with minimal or maximum modulation depending on whether there is a short-circuit or an interruption, and on the programmed mode of operation.	
		side measuring range	Check sensor	
-	х	Sensor2 Interruption / short circuit in the sensor leads or sensor values measured are out- side measuring range	The device works with minimal or maximum modulation depending on whether there is a short-circuit or an interruption, and on the programmed mode of operation.	
	Copera- tion - - X - - X	OperationFailureXX-XXX-X-X-X-X	PreventionFailureOpera- tionFailureNo line voltage Jumper J1 for USB interface pluggedX-Xfault in Eprom-Xfault EEP damagedXXXEEP data incorrectly-XSensor 1 Interruption / short circuit in the sensor leads or sensor values measured are out- side measuring range-X-XXSensor2 Interruption / short circuit in the sensor leads or sensor values measured are out- side measuring range	



Display	Relais switches *		Cause	Reaction of Controller	
	Opera-	Failure		Adjustment	
	tion		Aujustment		
External error * EC Motors Filter Frost protection Adiabatik Firealarm Pressure switch Gas alarm Water alarm RCD	-	x	X Alarm from external contact Device continues working unch check contacts.		
	1	Mess	ages for programmed limits	5	
Modulation Filter **	-	х	Limit alarm modulation	Device continues working unchanged. Calculation depending on modulation	
Lmt E1 min Filter **	-	Х	Limit indication minimum Signal actual value at "E1" below setting	Device continues working unchanger P Limit indication depending on set ting or sensor signal.	
Lmt E1 max. Filter **	-	Х	Limit indication maximum Signal actual value at "E1" above setting	Device continues working unchanged. Control Content indication depending on set- ting or sensor signal.	
Lmt E2 min. Filter **	_	х	Limit indication minimum Signal actual value at "E2" above setting	Device continues working unchanged. C Limit indication depending on set- ting or sensor signal.	
Lmt E2 max. Filter **	-	х	Limit indication maximum Signal actual value above setting	Device continues working unchanged Limit indication depending on set- ting or sensor signal.	
Offset 1 Filter **	-	х	Limit alarm deviation from Offset 1 too high	Device continues working unchanged Limits depending on the deviation from the setpoint.	
Offset 2 Filter **	-	x	Limit alarm deviation from Offset 2 too high	Device continues working unchanged. Calculation the deviation from the setpoint.	
When networking via the displayed. These depend Example:	For operation as MODBUS Master When networking via the MODBUS Master interface, the individual error messages of the members are displayed. These depend on the type of member ((@) operating instructions of the respective device). Example:			r nessages of the members are s of the respective device).	
Error MODBUS Com Fan: 8	-	х	Connection to the MODBUS Master interface interrupted Entered member count too high	Device continues working unchanged. Check member count Check MODBUS connection.	



Display Relais switches *		Cause	Reaction of Controller	
	Opera- tion	Failure		Adjustment
Motor fault Fan: 3	Motor fault Fan: 3-XExample for motor fault at member with address 3The unc Res ope con		The control module continues running unchanged. Reset required on the member ( P operating instructions of the device concerned).	
Line Fault Fan: 6	-	х	Example for line failure at member with address 6	The control module continues running unchanged. Check line supply of member.

\* Alternative display texts for error message via external contact P Controller Setup / display text for external message.
 \*\* Alternative display texts for limit alarms P limits function 3L



# 13 Enclosure

# 13.1 Technical data

Туре	CXE/AVC MODBUS			
Part-No.	37256 (320053-42)			
Line voltage	1 ~ 230 V (-15 % bis +10 %), 50/60 Hz			
Weight	0,9 kg			
Input resistance for sensor or signal	for 0 - 10 V input: R <sub>i</sub> > 900 kΩ			
set for the rotational speed (E1, E2)	for input 4 - 20 mA: $R_i$ = 250 $\Omega$ (max. load 500 $\Omega$ )			
Voltage supply e.g. for sensors	+24 V (-30+20 %), I <sub>max</sub> 70 mA			
Analog output (A1, A2 0 - 10 V)	Load resistance (load) > 5 k $\Omega$			
	Short-circuit proof, short-circuit current = 24 mA			
Digital inputs (D1, D2)	R <sub>i</sub> approx. 7.8 kΩ			
	Input current typ. 2.5 mA			
	Voltage range high level: 7.119 V DC			
	Voltage range low level: 02.7 V DC			
Max. heat dissipation	approx. 10 W			
Max. line fuse	10 A			
Max. permissible ambient temperature	55 °C			
Min. permissible ambient temperature	0 °C (if mains voltage is not switched off up to -20 °C)			
Permissible rel. humidity	85 % no condensation			
Electromagnetic compatibility for the	Interference emission EN 61000-6-3 (domestic household applications)			
standard voltage 230 / 400 V accord- ing to DIN IEC 60038	Interference immunity EN 61000-6-2 (industrial applications)			
Housing protection	IP54			

# Connectable conductors (information for all terminals)

		Cross section min.	Cross section max.				
	Terminal range, rated connection	0.13 mm <sup>2</sup>	1.5 mm <sup>2</sup>				
Pusn-in Terminals	Wire connection cross section AWG	AWG 24	AWG 16				
	Solid H05(07) V-U	0.2 mm <sup>2</sup>	1.5 mm <sup>2</sup>				
	Flexible H05(07) V-K	0.2 mm <sup>2</sup>	1.5 mm <sup>2</sup>				
	With wire end ferrule DIN 46 228/1	0.25 mm <sup>2</sup>	1.5 mm <sup>2</sup>				
	Wire plastic collar ferrule DIN 46 228/4,	0.25 mm <sup>2</sup>	0.75 mm <sup>2</sup>				
	Rigid conductors and conductors with wire end ferrules can be plugged into the terminal without tools. Use the flexible conductor for connection and the push button for release.						
	Stripping length: 8 mm						
The data refe	r to the connection possibilities of the terminals. The necessary conductor c	ross section must b	e dimensioned				

according to the respective prevailing conditions.


#### 13.2 **Connection diagram**



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- Line 1 2
- Digital inputs for potential-free contacts Outputs (I<sub>max</sub> = 2 mA): A1 pre-programmed control output e.g. for controlling a speed controller. Fans with integrated controller and input 0 -10 V can be activated directly. A2 pre-programmed for constant voltage +10 V Inputs E1 + E2: 0...10 V, 0...20 mA, 4...20 mA, TF.. (KTY, Pt1000) Contact rating max. AC 250 V 2 A (ohmic load) Winter U for USD interface (Decthorder) 3
- 4
- 5
- Jumper J1 for USB interface (Bootloader) 6

### Attention!

Plug the jumper J1 to both PINs only for a software update via USB interface. The device will not switch on if this jumper is plugged to both PINs!

Do not replug the jumper under voltage, observe the safety instructions!





## 13.3 Dimensions [mm]







# 13.4 Index

Α		Mode	16
addition, addressed	12 13	<b>O</b>	0
Average calculation	31	P	9
В		- P component	55
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D		-	
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К		W	
K Factor	44	wintertime	83
L			
Limit	53		
Limits	11		
Μ			
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MODBUS Master	53 12 87		
MODBUS Slave	12, 86		



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# 13.5 Manufacturer reference **( €**

Our products are manufactured in accordance with the relevant international regulations. If you have any questions concerning the use of our products or plan special uses, please contact:

Systemair Industrievägen 3 73930 Skinnskatteberg Telefon:+46 (0) 222 440 00 Telefax:+46 (0) 222 440 99 mailbox@systemair.se www.systemair.se

